





Making Space-based Sensors Discoverable on the Internet Using A Service Oriented Architecture and Open Geospatial Consortium Standards

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White Paper for ESTO





Introduction

- NASA/GSFC prototyping open source software based on Open Geospatial Consortium (OGC) standards to enable user-centric geospatial sensor web services
- User can access:
 - Data from sensors (space-based, unmanned aerial vehicles and insitu)
 - Services to perform various levels of data processing
 - Models which describe how to create desired science products from available sensor data
- Science products/algorithms are registered on a catalog server and are easily discoverable, accessible, modifiable and extensible via service chains

Basic Concept



Reference Architecture for an Inter-Operable Sensor Web



Target EO-1 User Scenario

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EO1-GeoBilki

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- Department of Homeland Security (DHS) analyst requests fire, flood, ice breakup, and other features of interest to analyze emergency response in disaster area
- Client DSS Model queries catalog and finds sensor capabilities and processing services that can potentially supply the requested features
- Catalog returns EO-1 and other data sources as possible source via Catalog Services for the Web (CSW).
- Access to high resolution EO-1 data is granted based on user/role permission
- No recent EO-1 data is available for the disaster site, so satellite tasking is required and achieved (at no cost to DHS) via DSS Optimizing Scheduler and SPS service
- Analyst is notified via instant message that Hyperion/ALI data products are available. High resolution imagery is retrieved via SOS, WCS and WFS services
- Analyst requests data processing to extract desired features from EO-1 data and Workflow Engine executes data processing algorithms in response
- Processed features are overlaid on maps, annotated by the analyst, and shared with other users via blog, wiki, and/or forum

Benefits of Architecture

	Current Way	Vision for New Way
Method to develop new algorithms	Custom (license fees)	Open source building blocks (no fees)
Interoperability	Low	High
Cost to create & implement new algorithms/service chains	High	Low
Data storage and transfer requirements	High: Store/archive and transfer all sensor data	Modest to Low: Filter and transfer only needed features; archive virtual produc
Ease of finding and reusing existing algorithms	Difficult	Easy with automatic discovery