

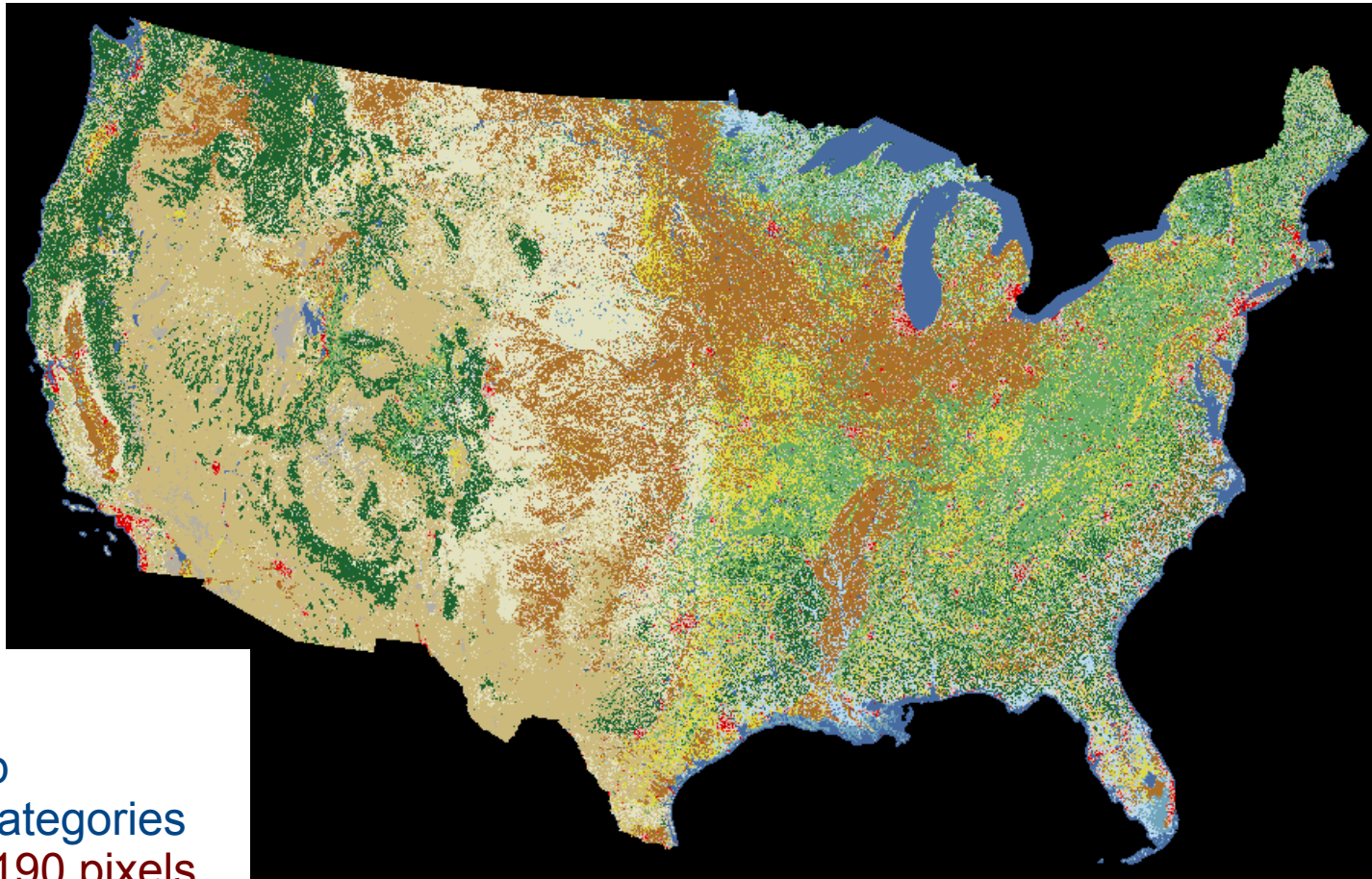
GeoPAT – Pattern-based GIS Software for understanding content of large Earth science datasets

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Example of a dataset we are interested in



NLCD2011
categorical map
16 land cover categories
104,242 x 161,190 pixels

How to analyze such dataset **in its entirety**?

What **relevant** information can we extract from such dataset?

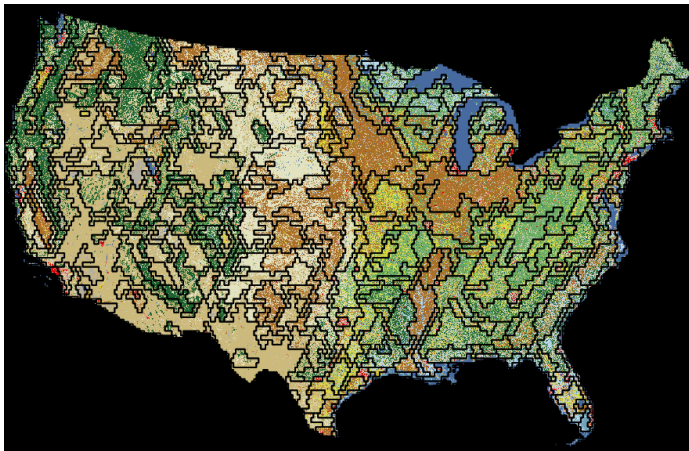
What are other, similar datasets?

What are the applications for such analysis?

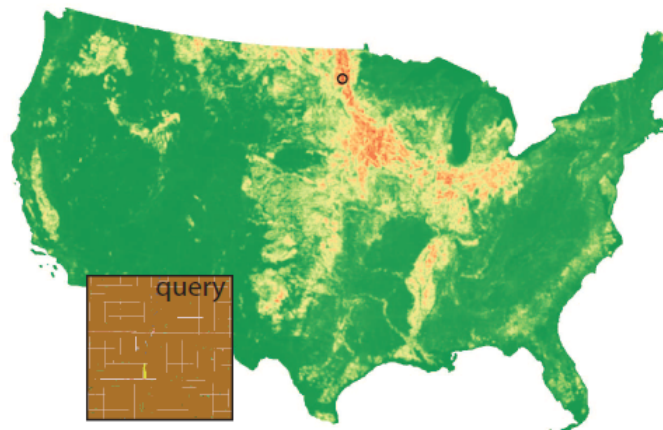
Some answers...

Tools relevant to analyzing NLCD in its entirety:

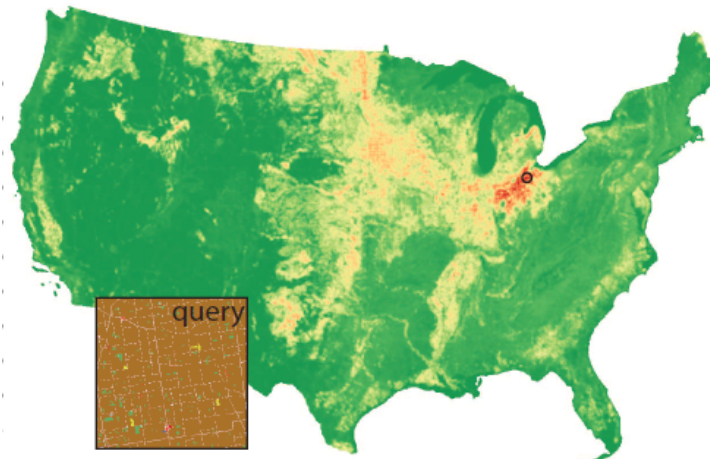
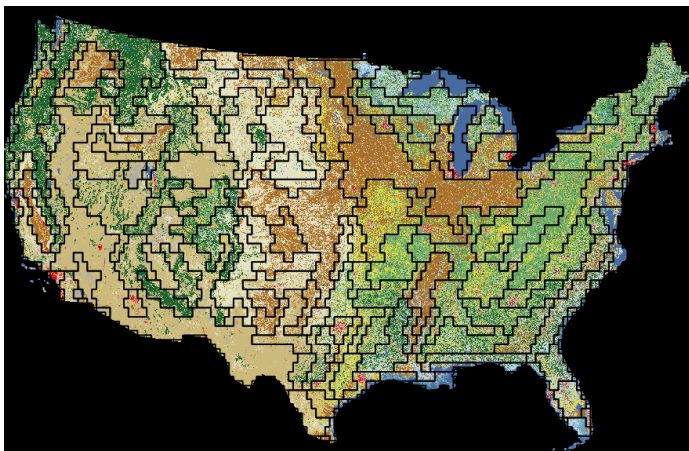
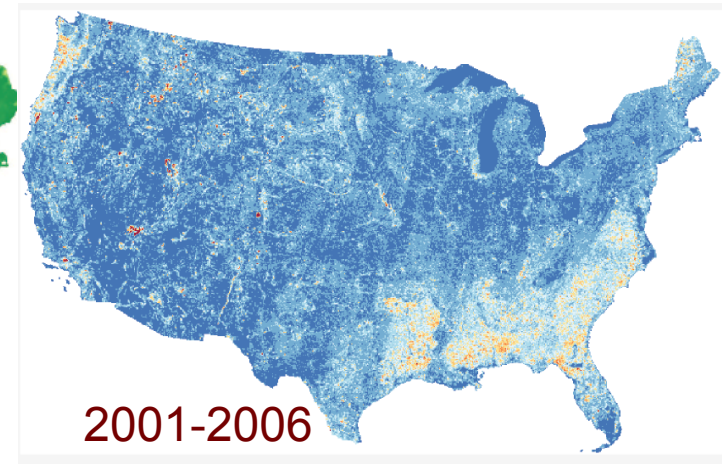
Segmentation into regions of homogeneous land cover patterns



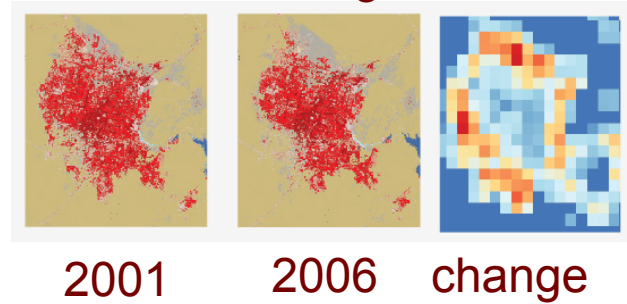
Spatial search



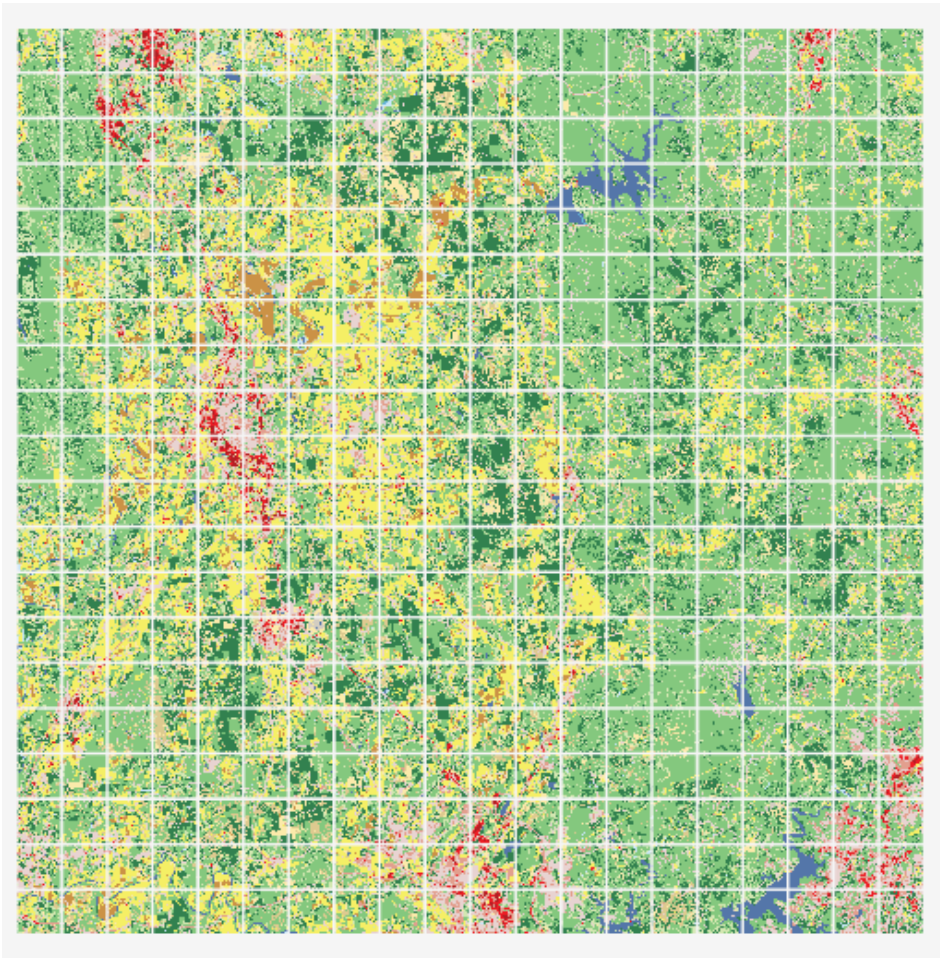
Temporal change



Las Vegas

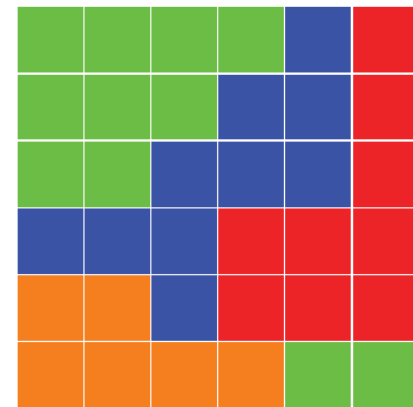


Basic concepts

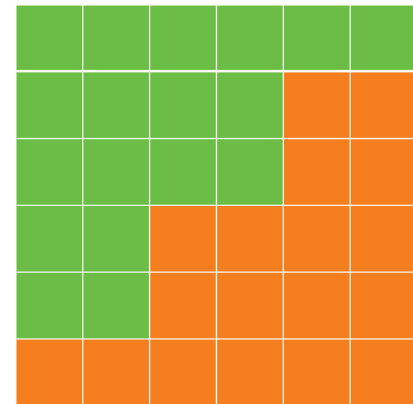


Grid of motifels

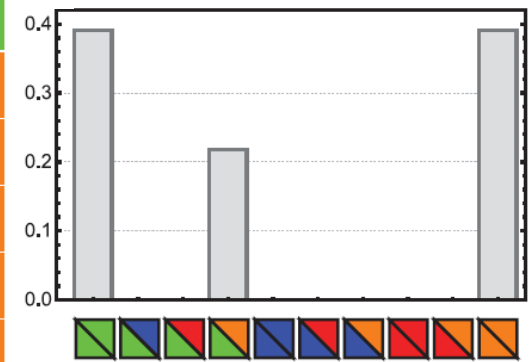
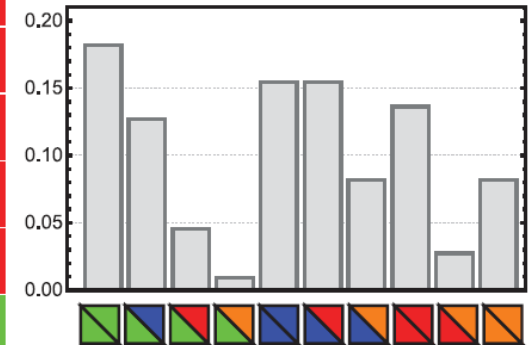
Motifel – elementary unit of analysis - a square block of pixels representing local landscape



motifel 1



motifel 2



histograms of features

Motifel is represented by histogram of features (co-occurrence, decomposition)

Distance between motifels is a distance between their histograms (Jensen-Shannon Divergence)

Difference between our method and object-based image analysis (OBIA)

object-based image analysis

works best for small scenes
identifies individual objects

well-veloped

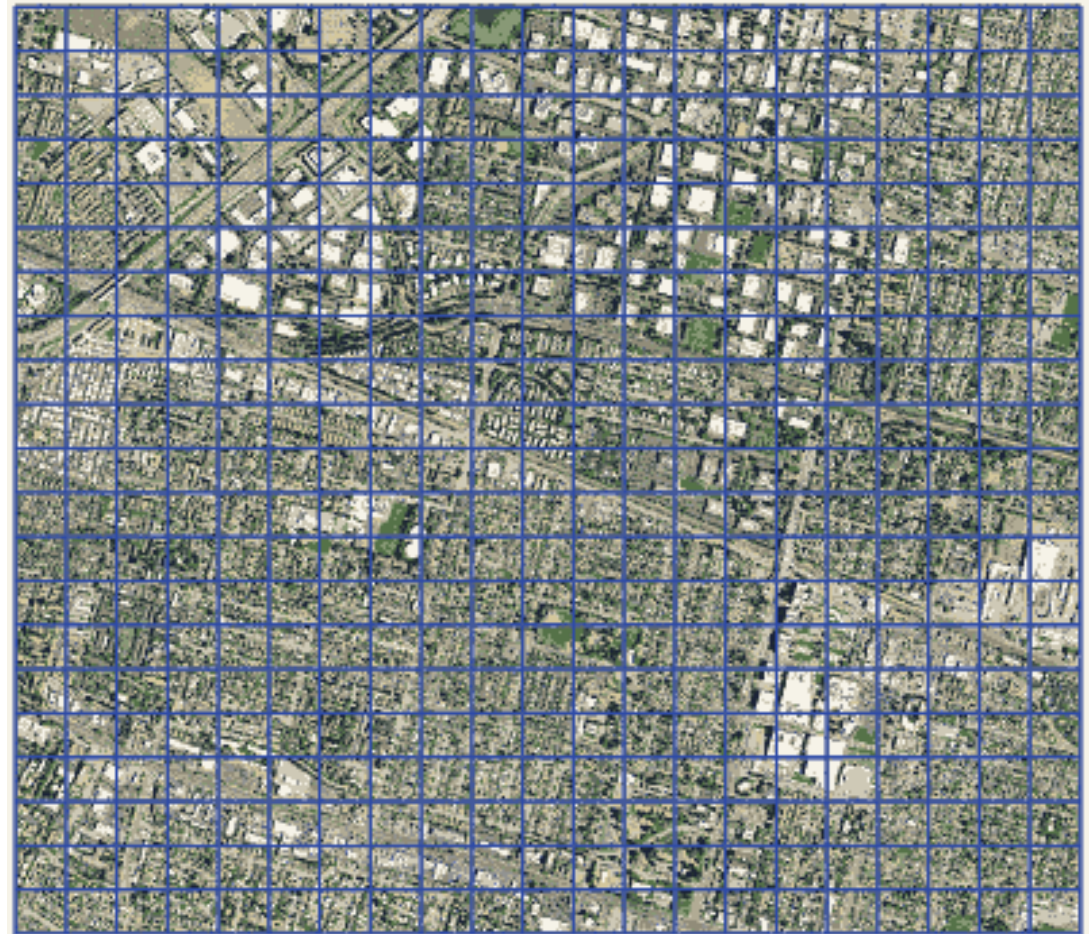


irregular objects having simple,
homogeneous content

complex object-based image analysis

works best for large scenes
identifies types of neighborhoods

our project



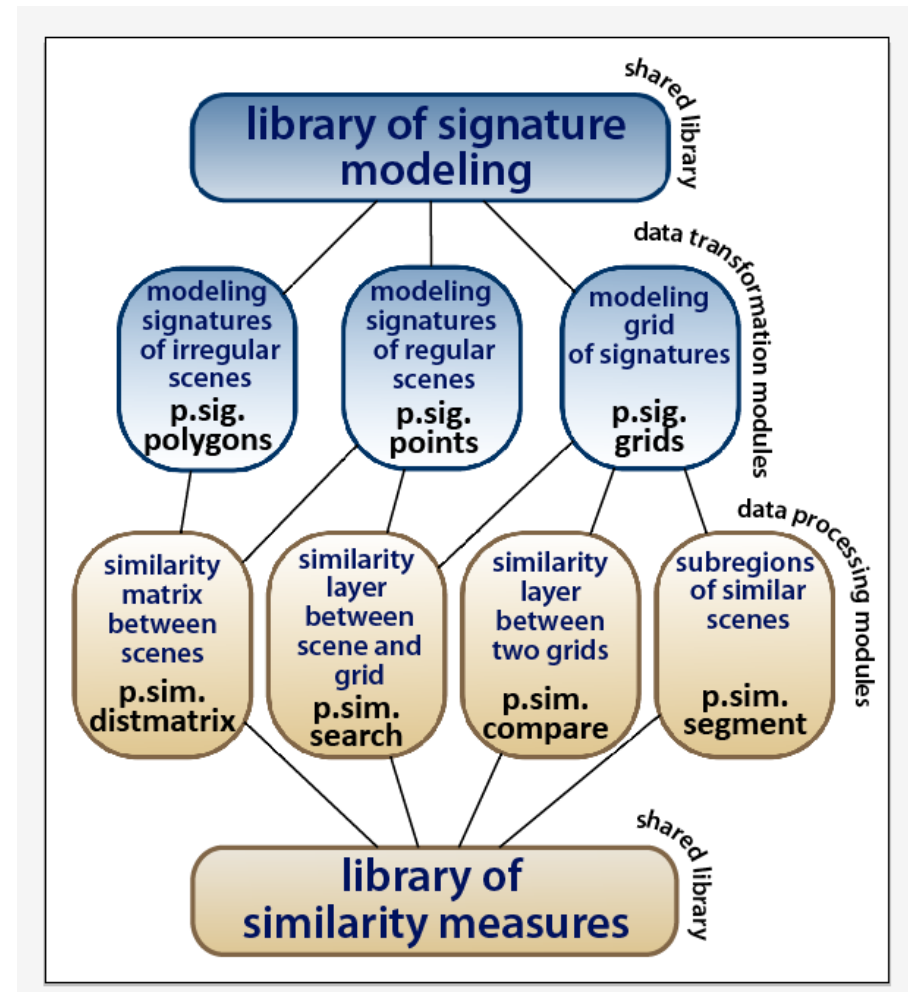
regular objects having complex,
inhomogeneous content

GeoPAT

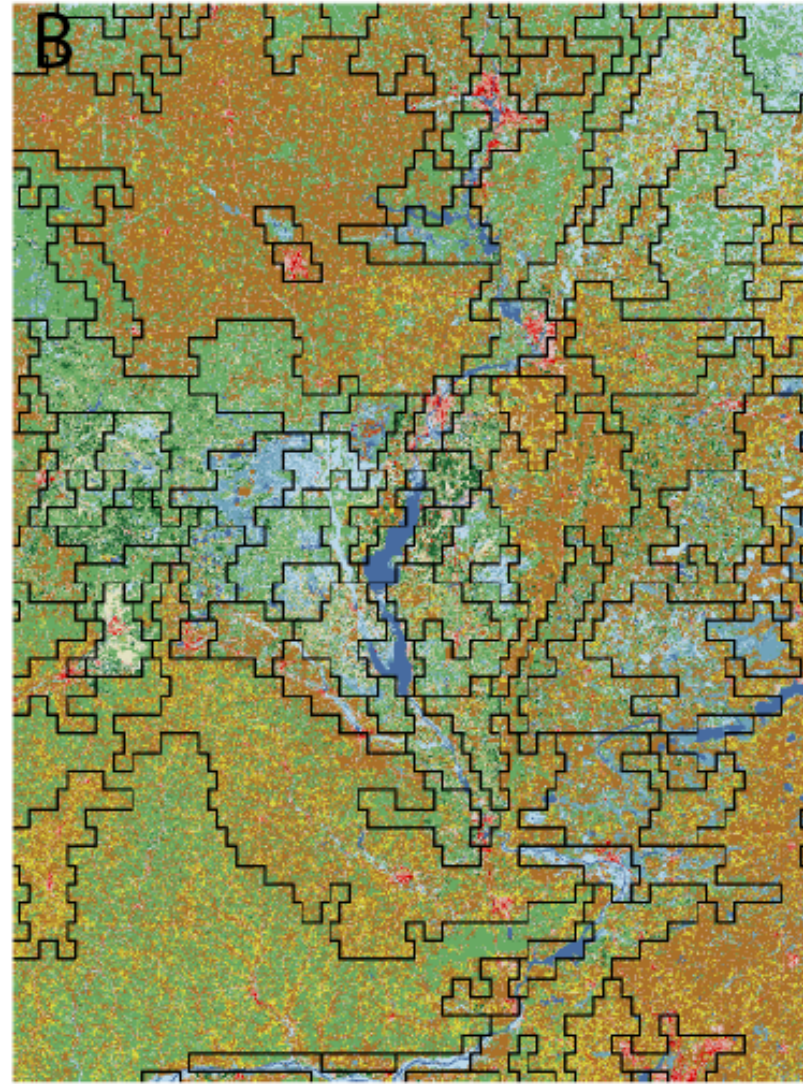
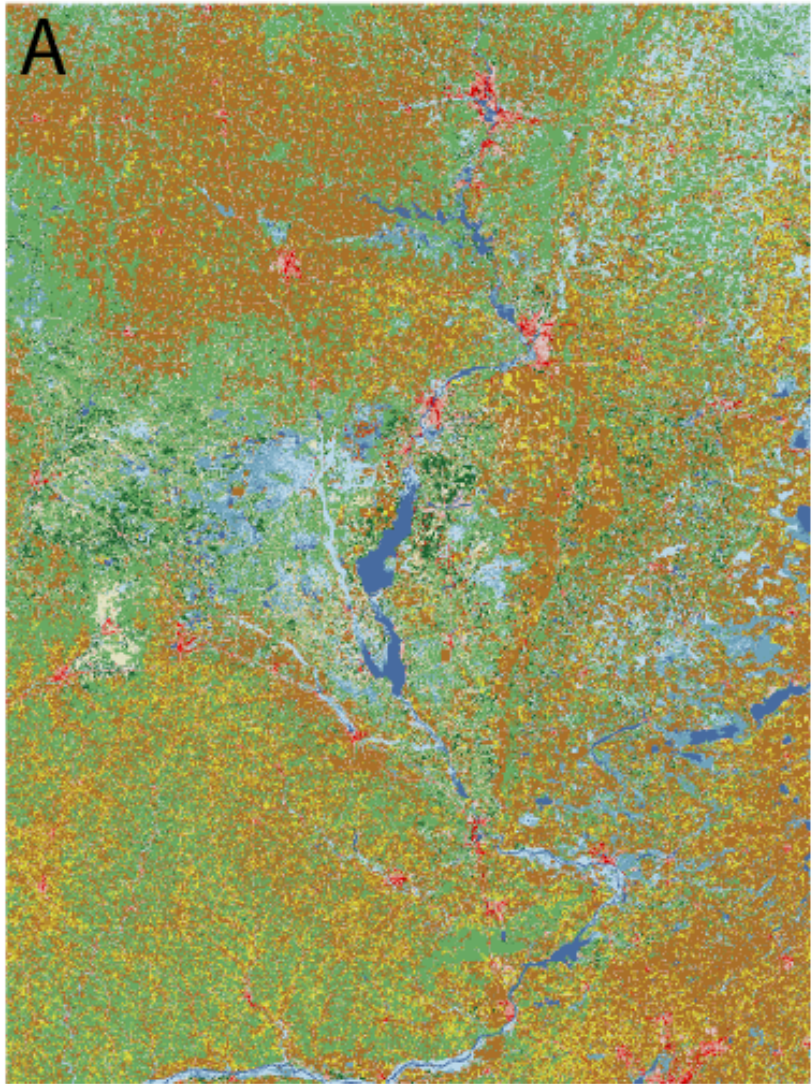
Geospatial Pattern Analysis Toolbox (GeoPAT) is a collection of GRASS GIS modules, written in C, for carrying out pattern-based geospatial analysis of large categorical spatial datasets.

We are developing GeoPAT 2, a stand alone version of our software, which does not require GRASS or Linux.

The new version has expanded functionalities, features brand new segmentation module, and will be optimized to work with Xeon Phi co-processor.



















Segmentation 1 of 8



0 50km

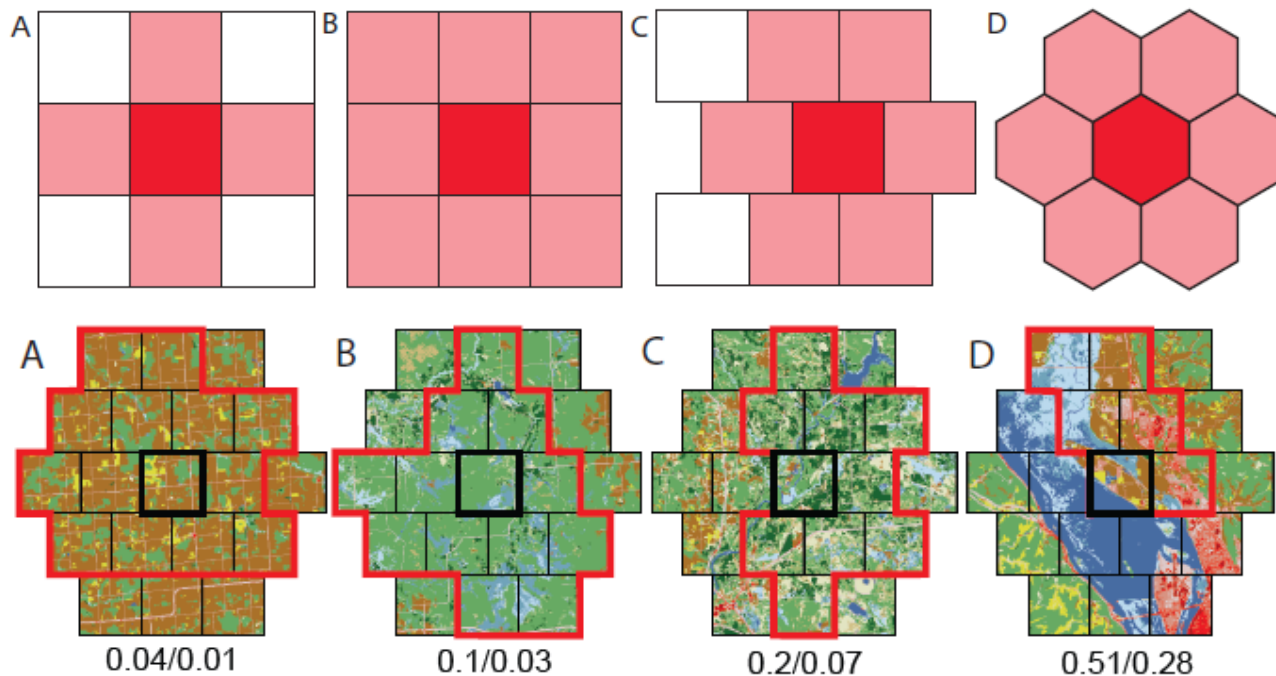
NLCD legend

-  open water (11)
-  ice/snow (12)
-  developed open space (21)
-  developed low intensity (22)
-  developed med. intensity (23)
-  developed high intensity (24)
-  barren land (31)
-  deciduous forest (41)
-  evergreen forest (42)
-  mixed forest (43)
-  shrub/scrub (52)
-  grassland (71)
-  pasture/hay (81)
-  cultivated crops (82)
-  woody wetlands (90)
-  emergent wetlands (95)

Segmentation 2 of 8

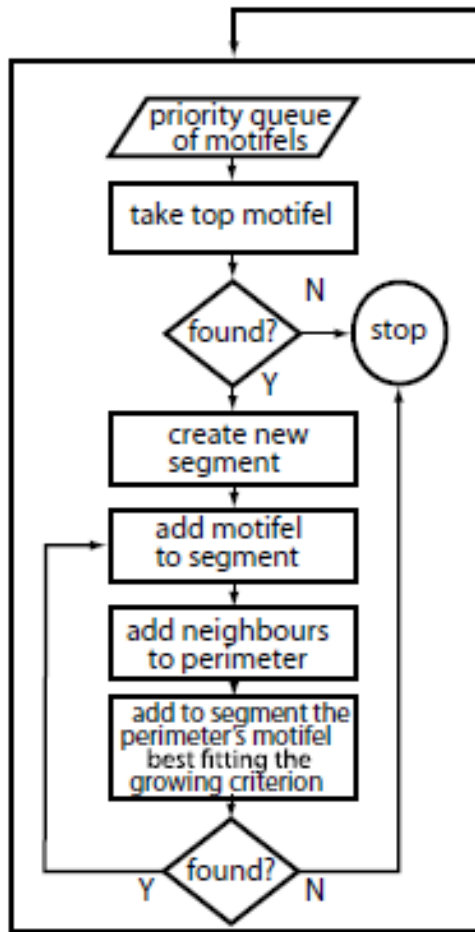
GeoPAT segmentation algorithm is based on the principle of seeded region growing (SRG) but introduces a number of novel features in order to make the SRG applicable to the task of pattern-based segmentation of categorical rasters:

1. Motifels instead of pixels (new representation and distance)
2. Brick-wall topology of grid
3. Novel method of constructing a priority queue for potential seeds and adoption of locally determined growth-stopping criteria for regions growing from these seeds

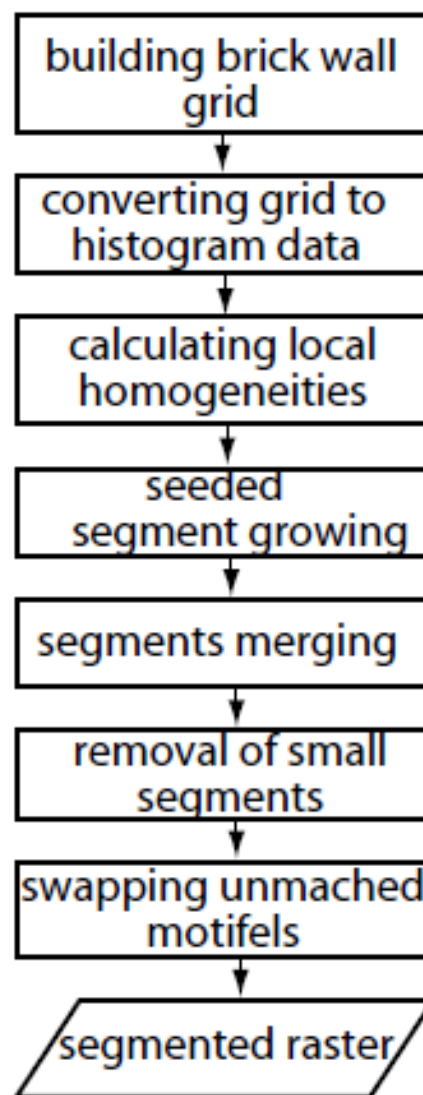


Segmentation 3 of 8

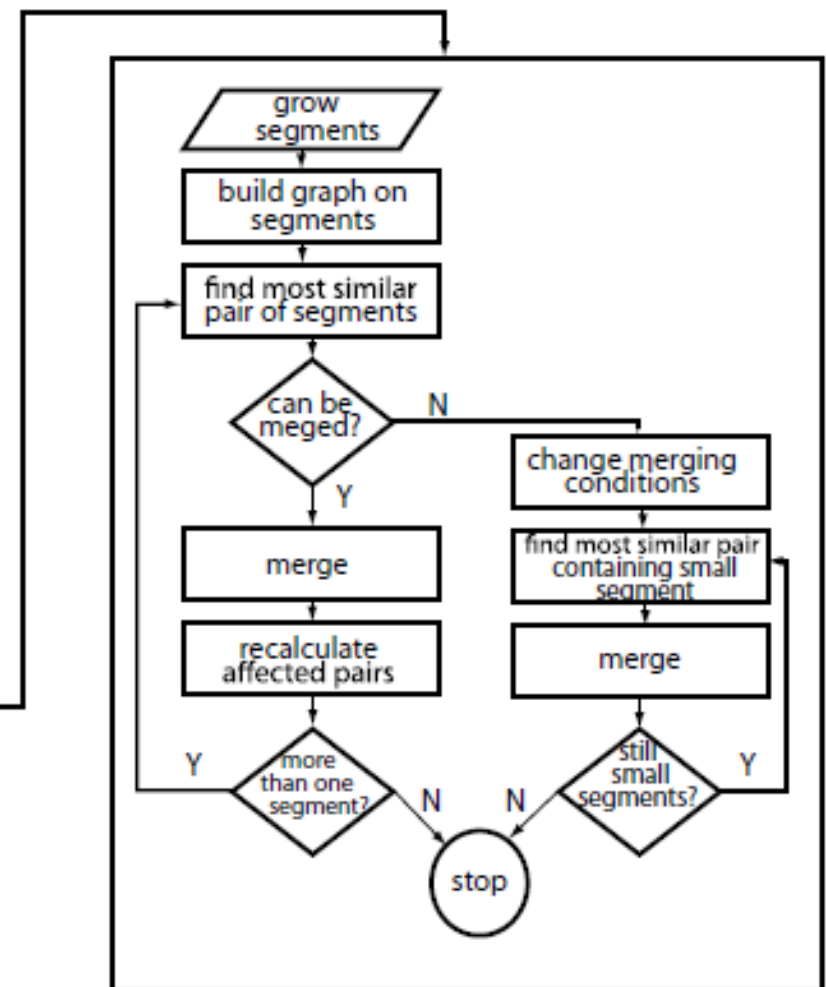
region growing



main process



region merging



Segmentation 4 of 8

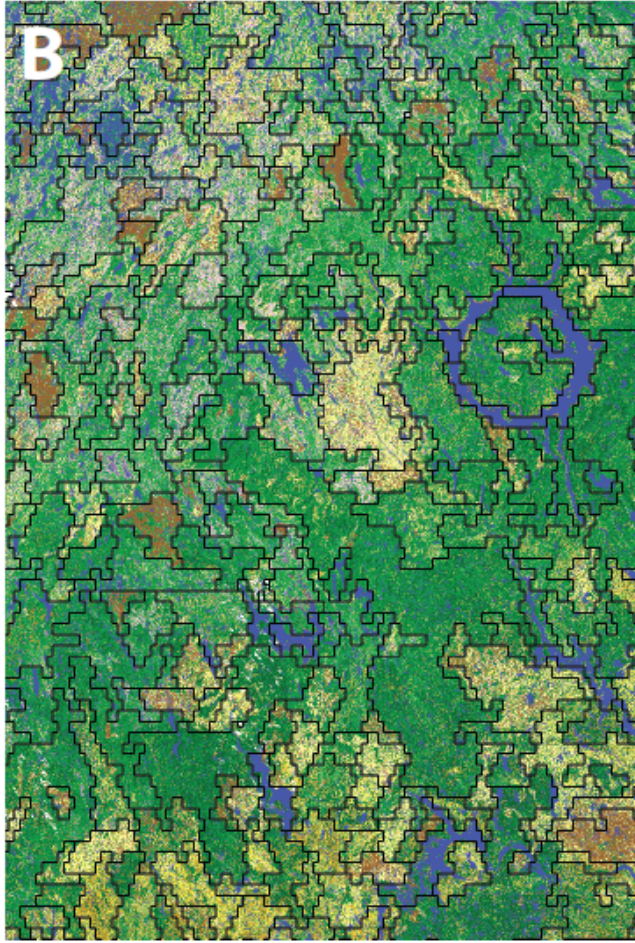
Dataset	Data size	Motifel	# segments	Total time
NLCD (exam.)	16896×16192	64	3135	3m 34s
		128	605	58s
		256	155	33s
		512	63	33s
NLCD2011 U.S.	104242×161190	128	24097	1h 48m
		256	6130	33m 11s
		512	1799	12m 3s
Topo. U.S.	104242×161190	128	26041	2h 11m
		512	4041	13m 24s
EOSD Canada	224400×130800	400	3399	33m 17s
LA image	41600×50200	200	2894	1h 23m

All calculations were performed on computer with Intel 3.4GHz, 4-core processor and 16 GB of memory running the Linux operating system.

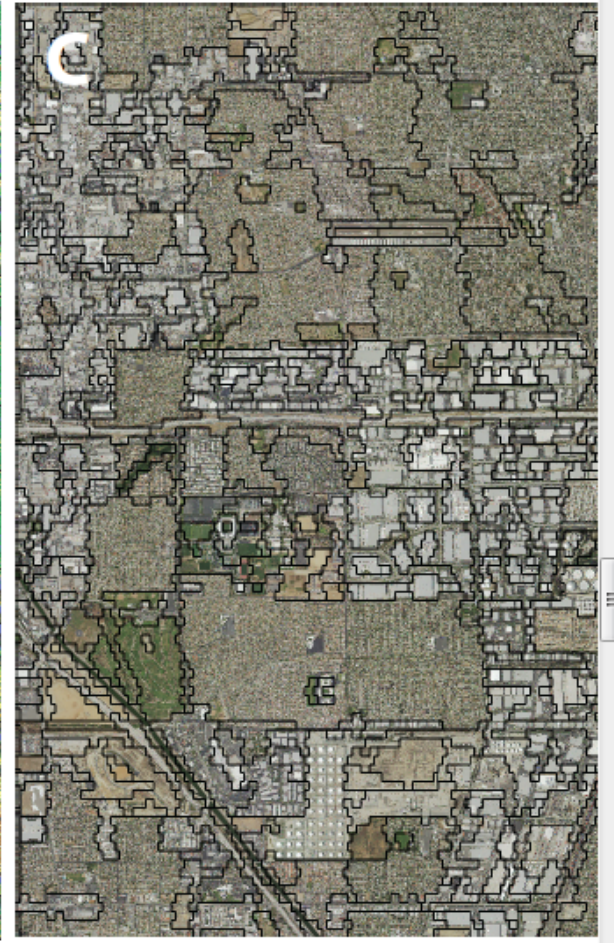
Segmentation 5 of 8



US topography 30m

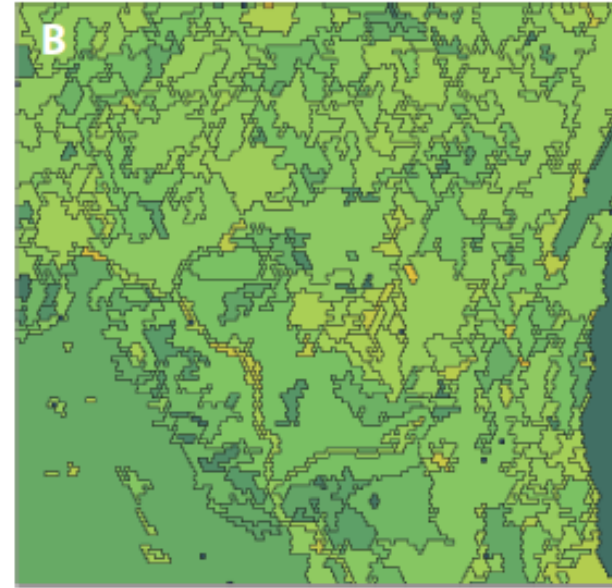
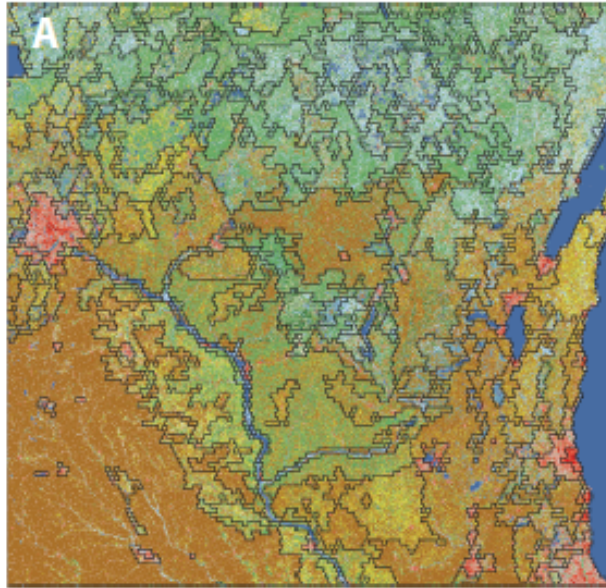


Canadian forest 30m

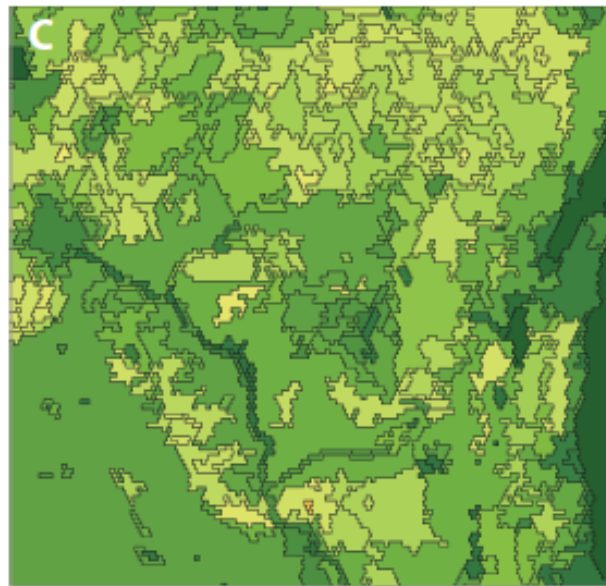
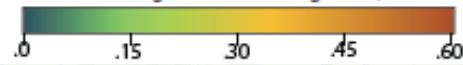


Los Angeles image 1m

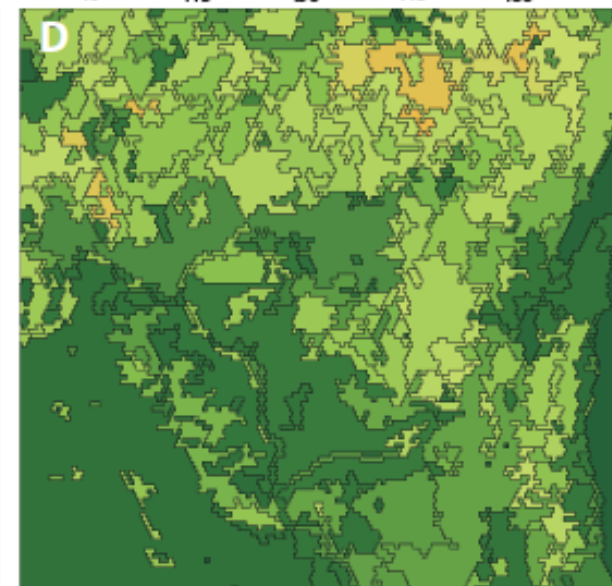
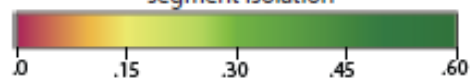
Segmentation 6 of 8



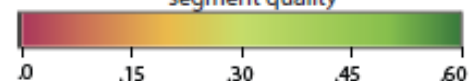
segment inhomogeneity



segment isolation

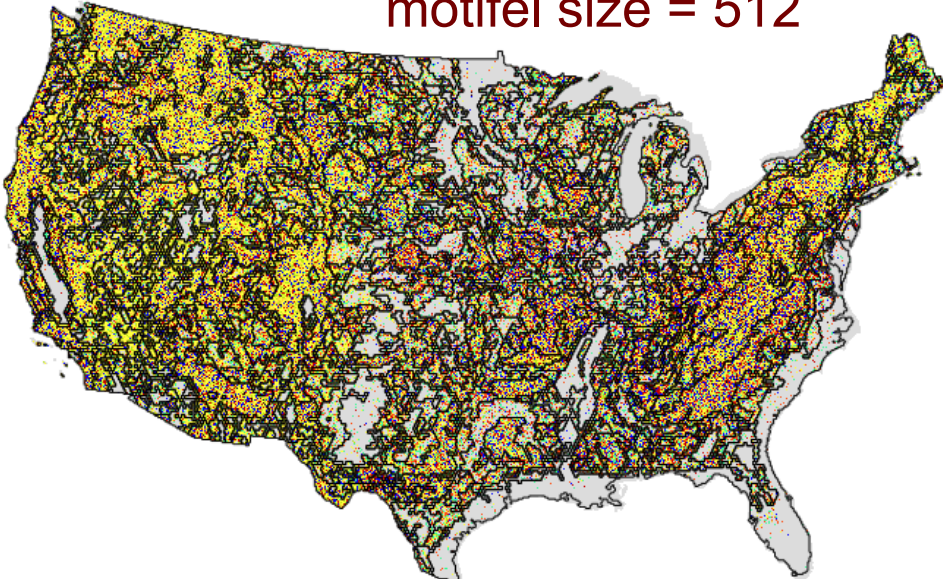


segment quality

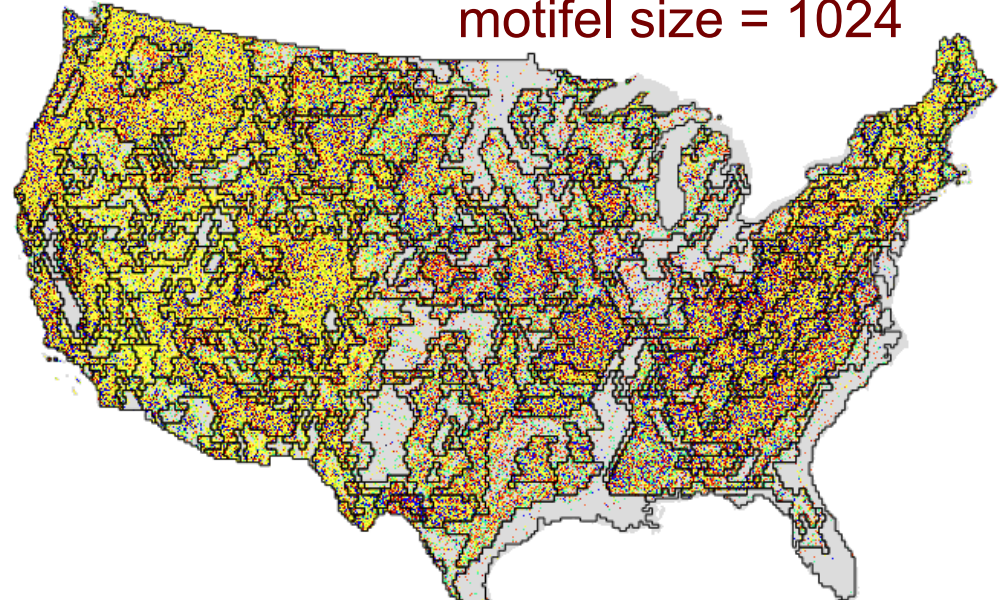


Segmentation 7 of 8

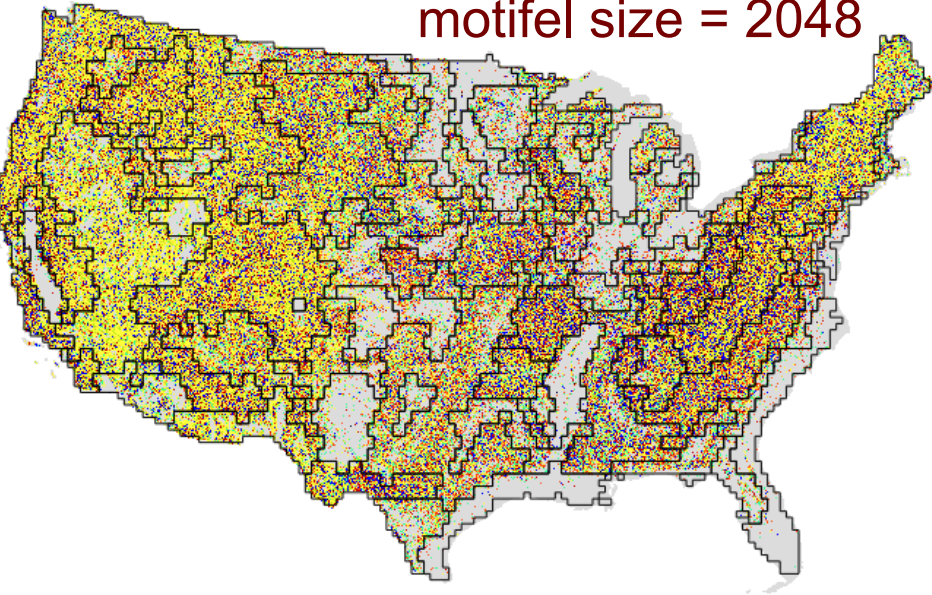
motif size = 512



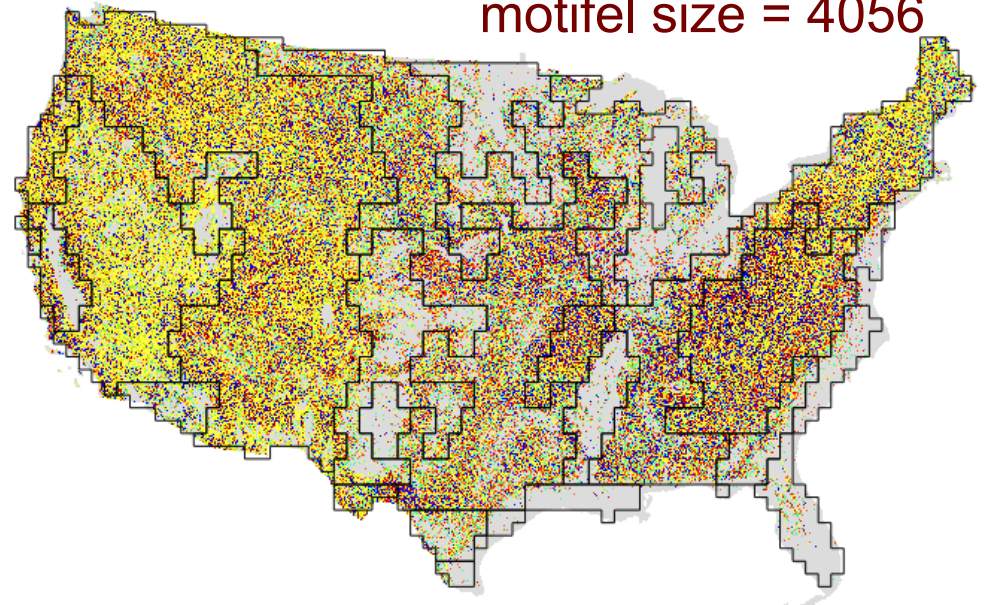
motif size = 1024



motif size = 2048



motif size = 4056



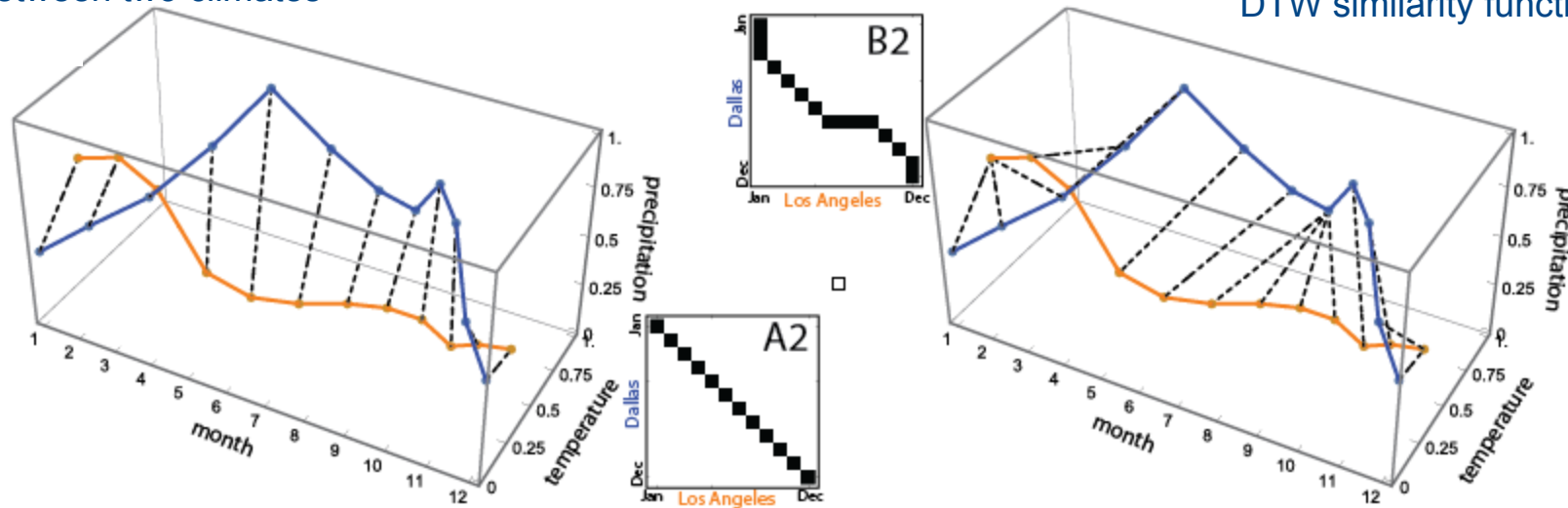
Multi-scale segmentation by changing the size of motif

Segmentation 8 of 8

Standard, Euclidean similarity function between two climates

Climate, Dynamic Time Warping

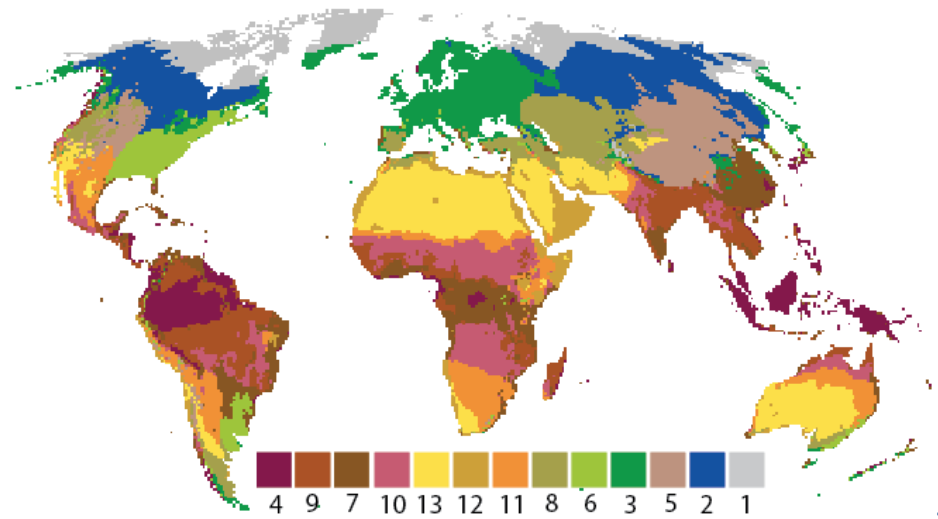
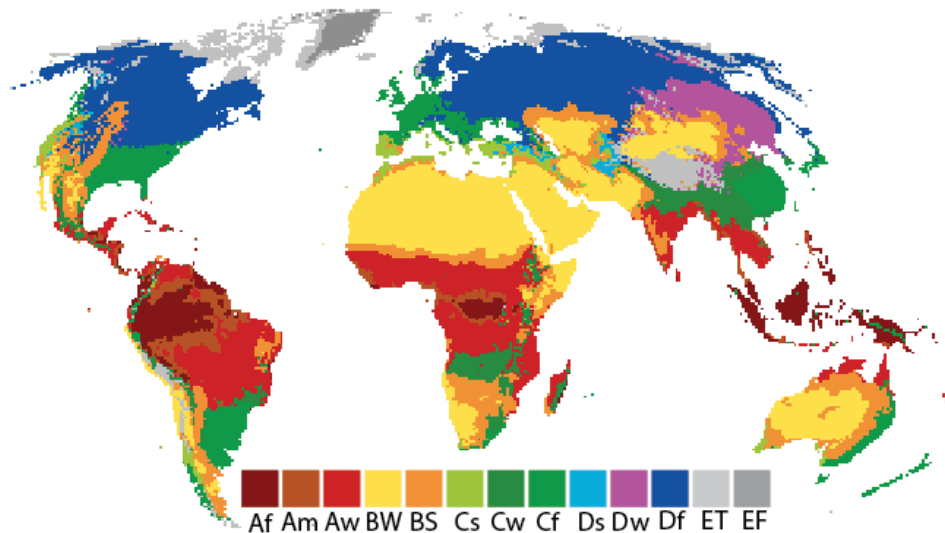
DTW similarity function



We calculate regionalization of world climates using a concept of climate as time series (temporal pattern) and utilizing the Dynamic Time Warping (DTW) as similarity function

Standard climate classification: Koppen-Geiger

Climate classification based on temporal patterns



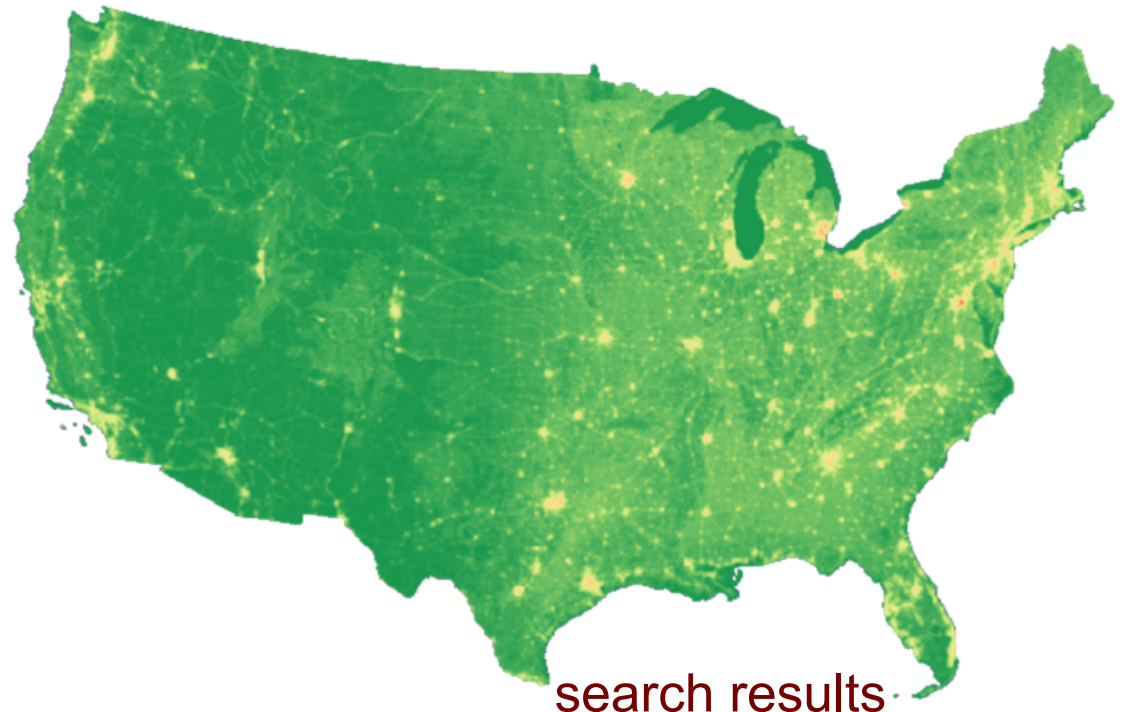
Search 1 of 5

GeoPAT is used to implement pattern-based searches as GeoWeb applications:

1. LandEx – search for similar patterns of land cover over the U.S. sil.uc.edu/webapps/landex_usa/
2. ClimateEx – search for similar climates over the world. sil.uc.edu/webapps/climatex/
3. TerraEx – search for similar landforms over the world (beta) sil.uc.edu/webapps/terraex/

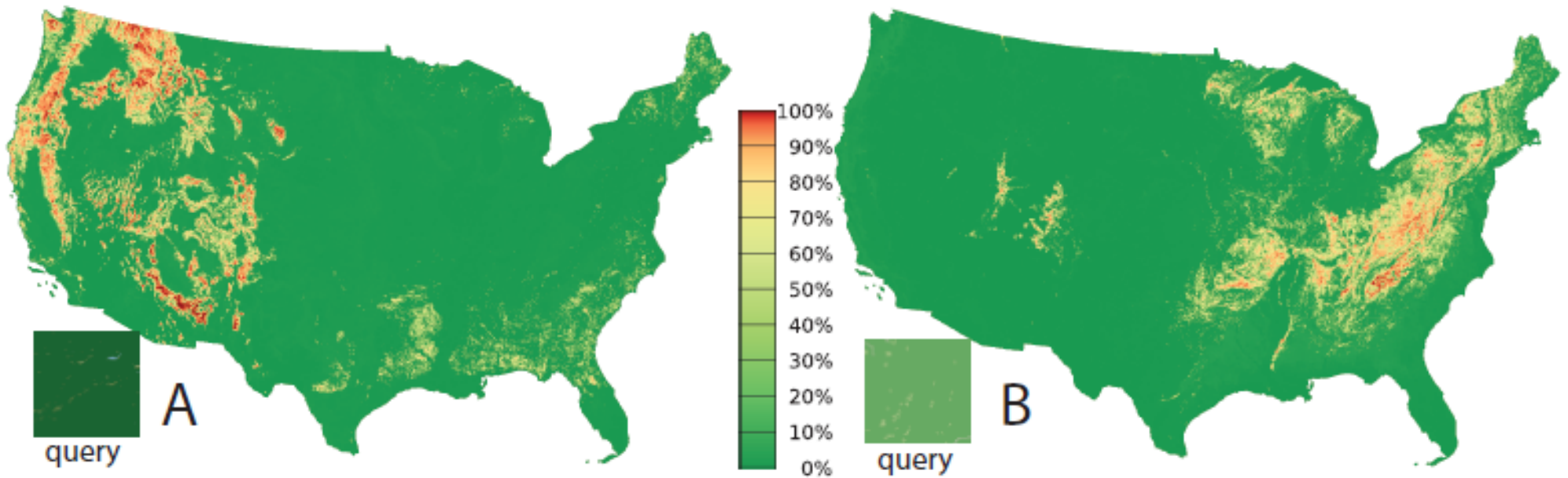


query – Washington DC



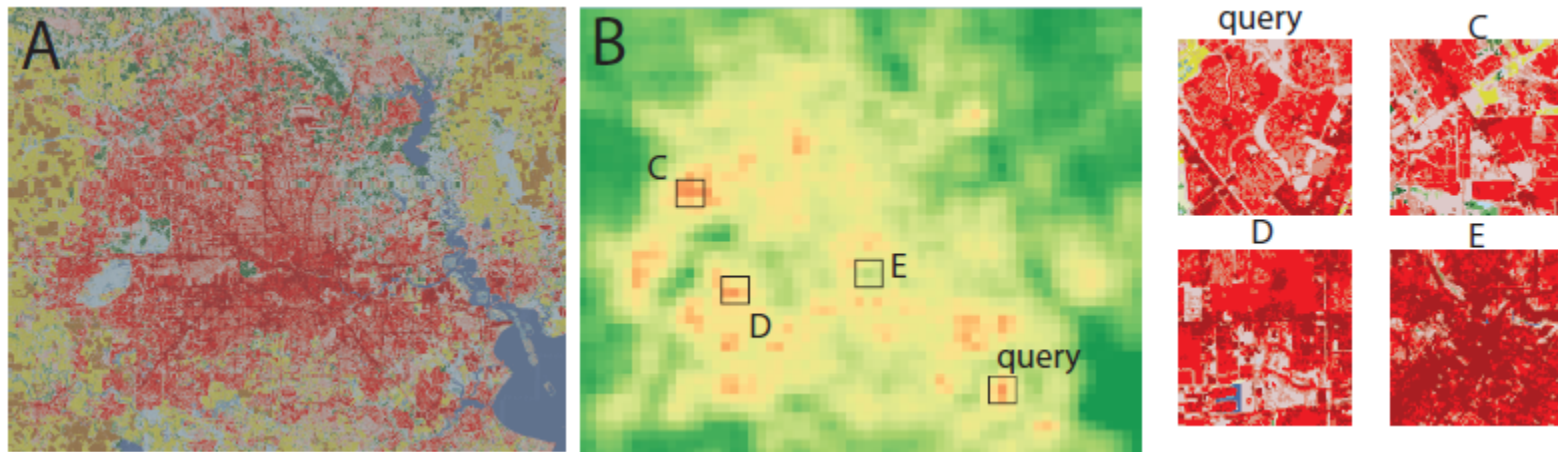
search results

Search 2 of 5



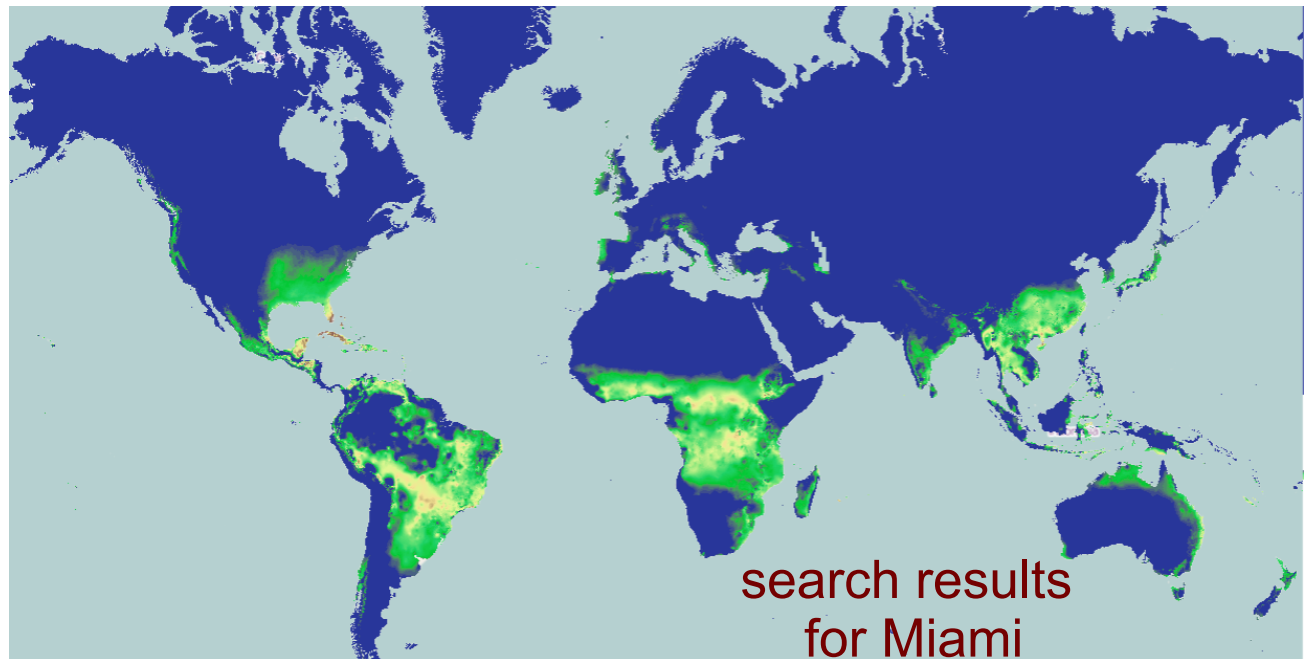
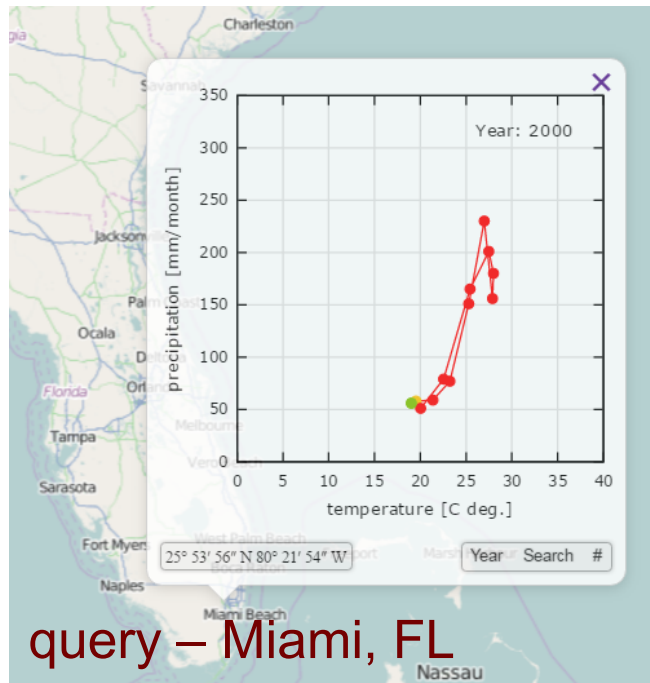
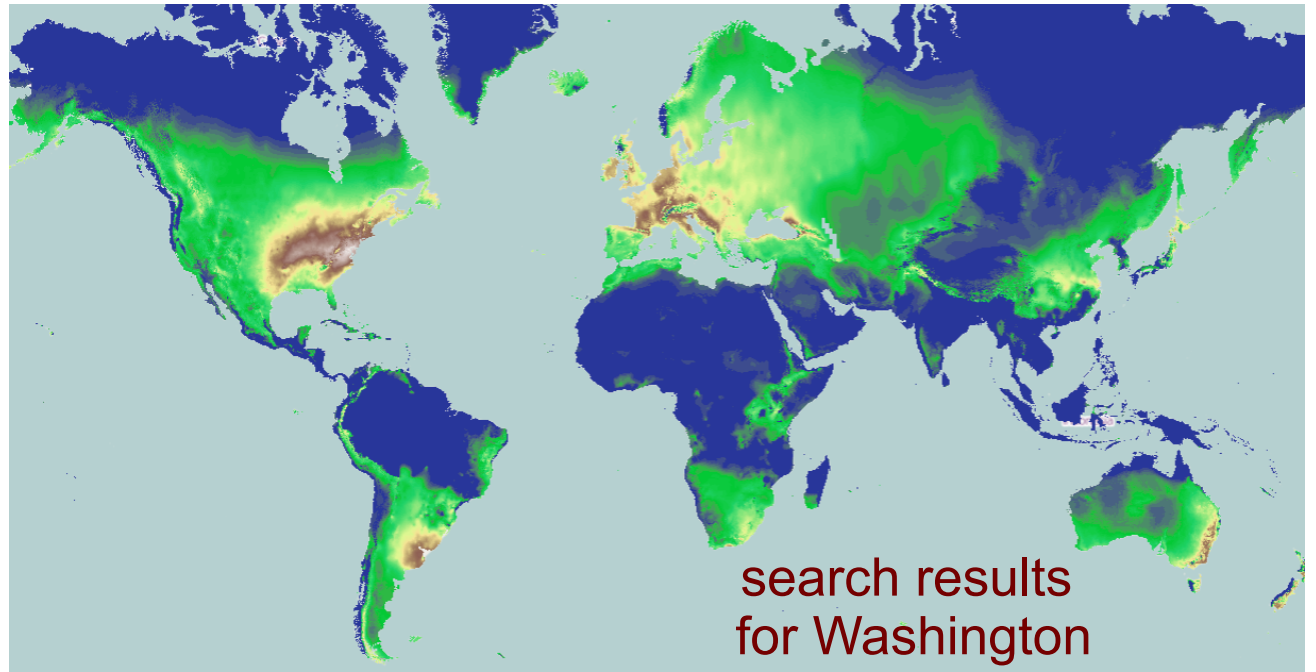
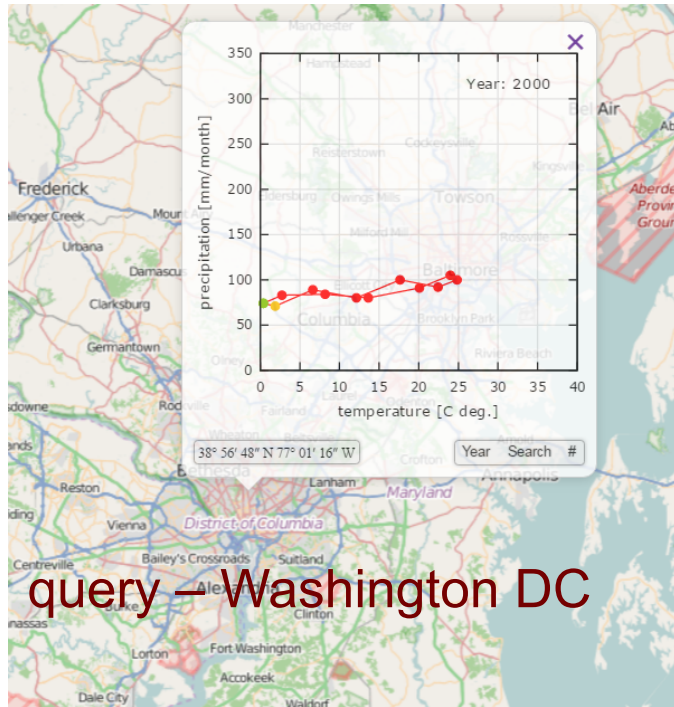
consolidated evergreen forest

consolidated deciduous forest

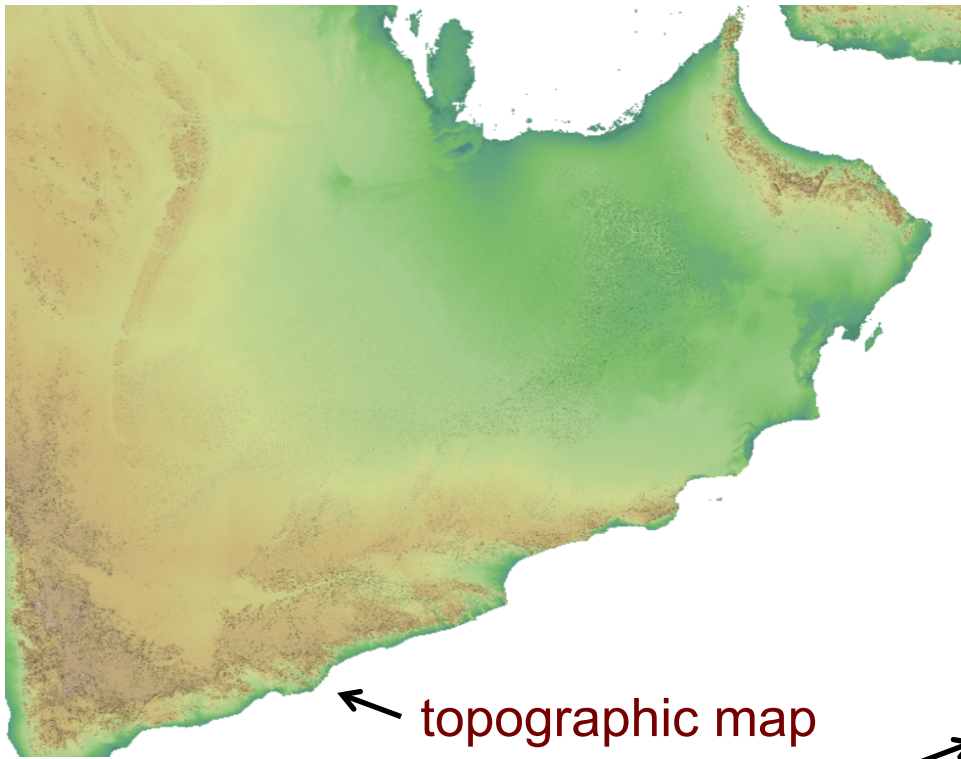


Search of similar urban landscapes in Houston, TX

Search 3 of 5

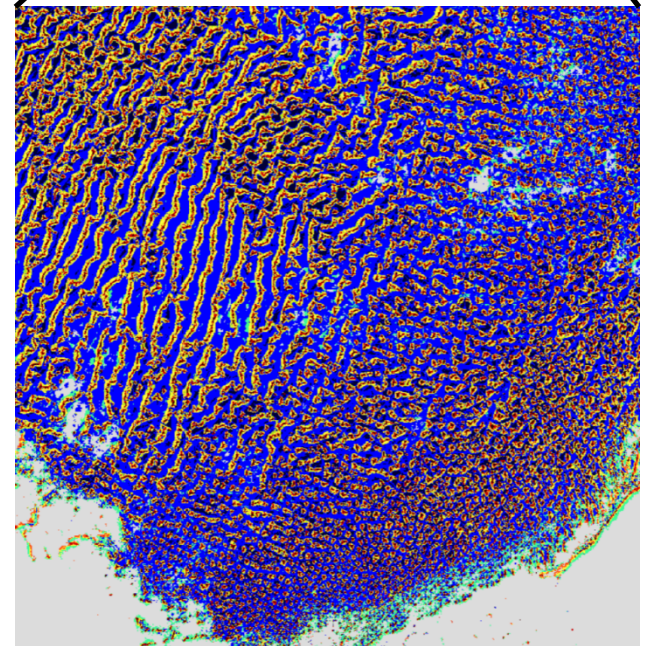
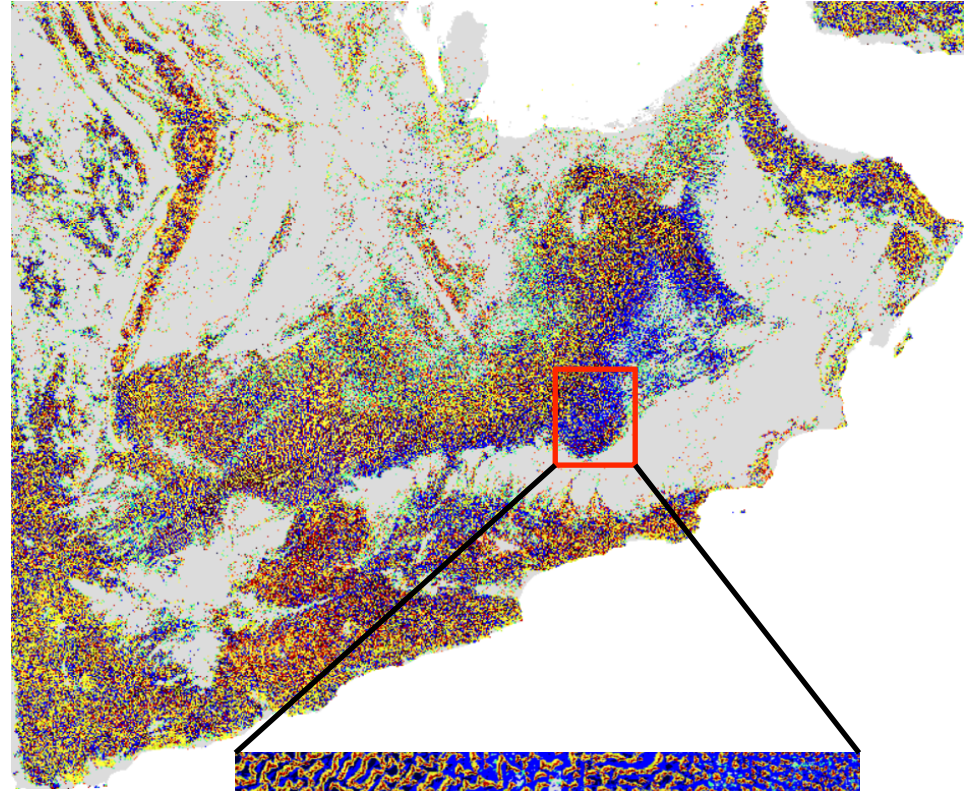


Search 4 of 5



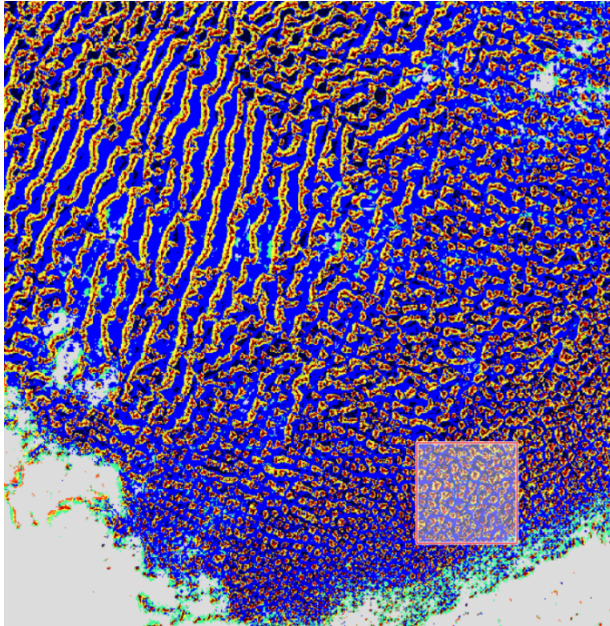
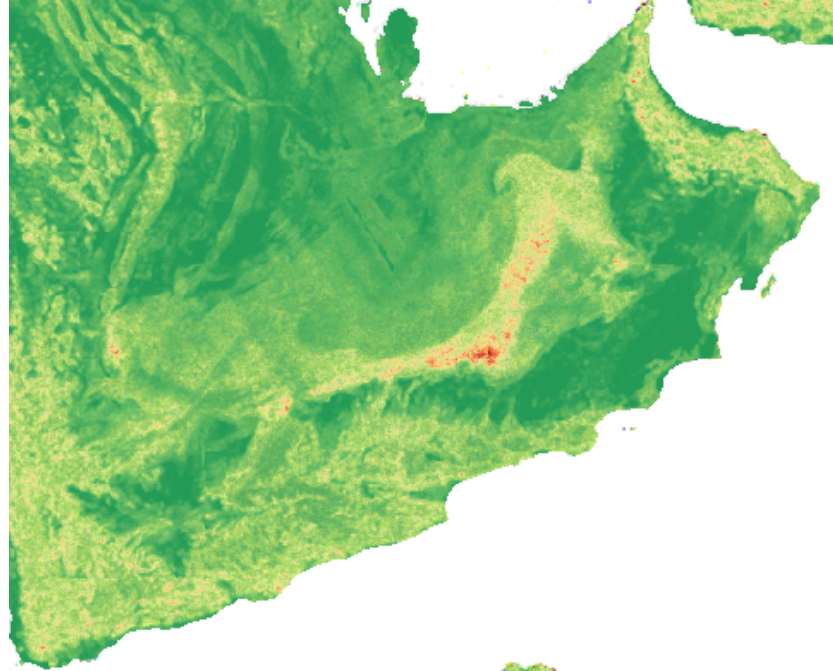
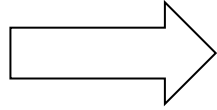
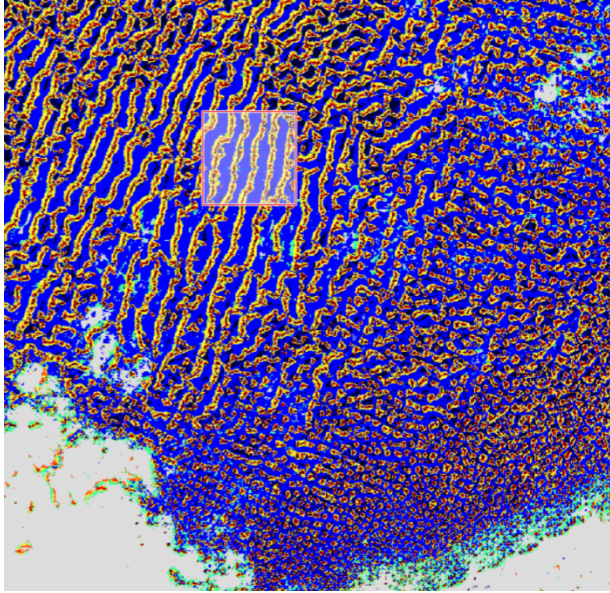
← topographic map
geomorphons map →

Saudi Arabia Empty Quarter

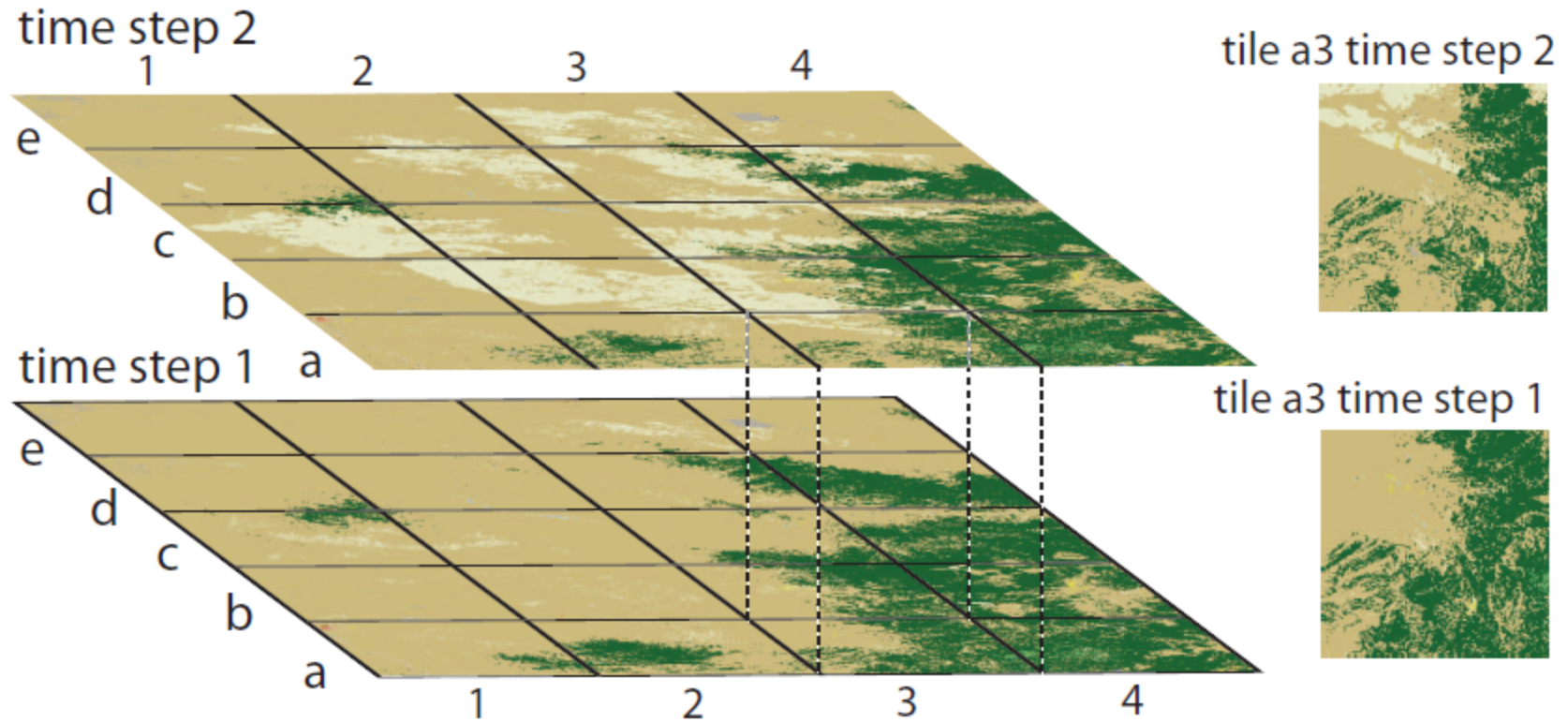


all examples computed online by TerraEx (sil.uc.edu) (beta)

Search 5 of 5

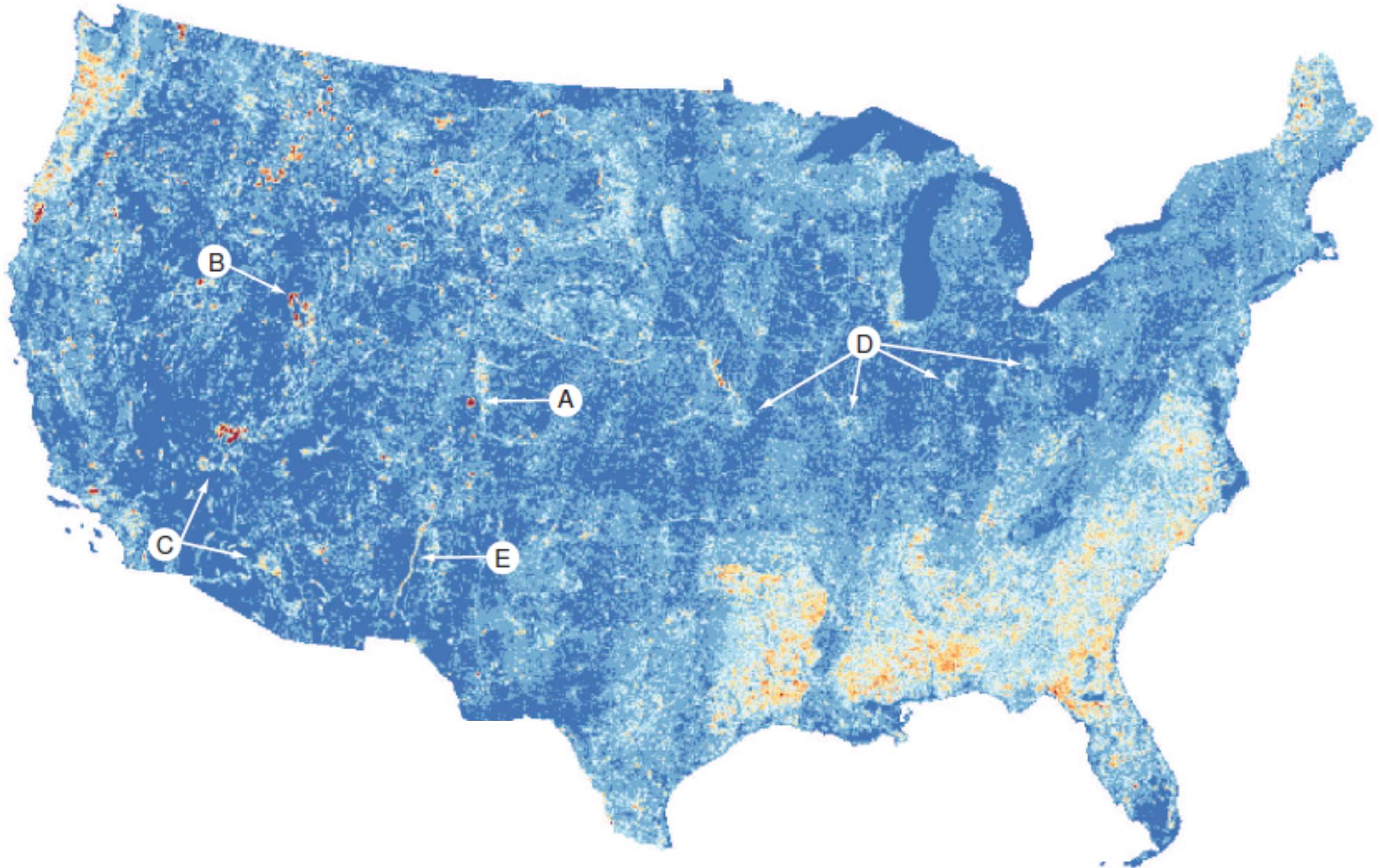


Change 1 of 5



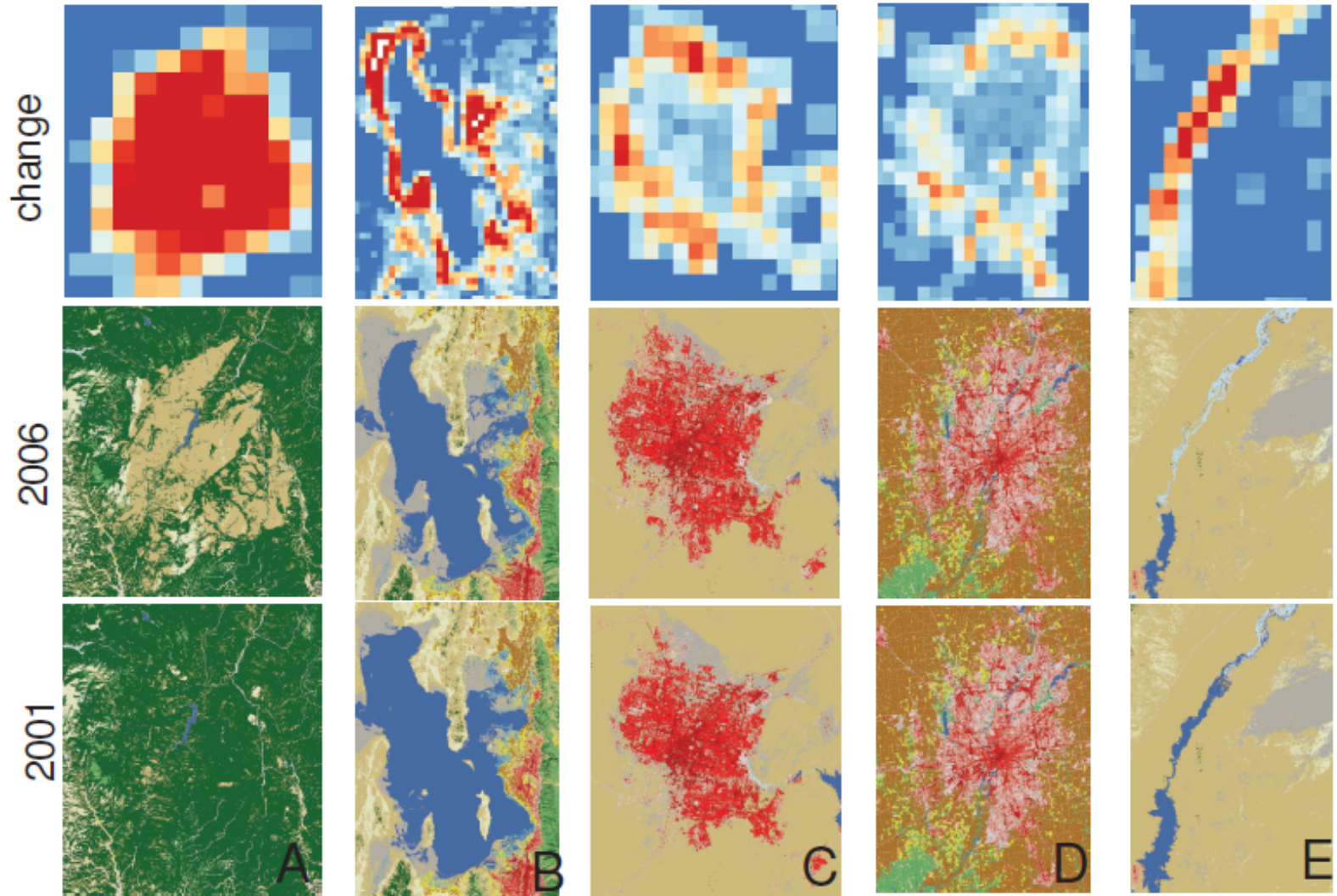
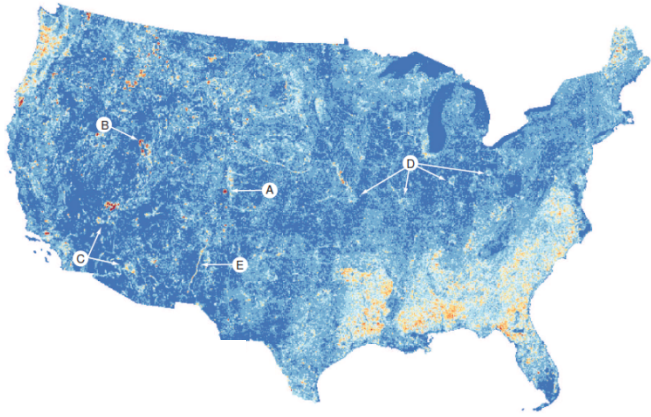
A degree of dissimilarity between the same locations (motifels) at two different times is a measure of change in pattern.

Change 2 of 5

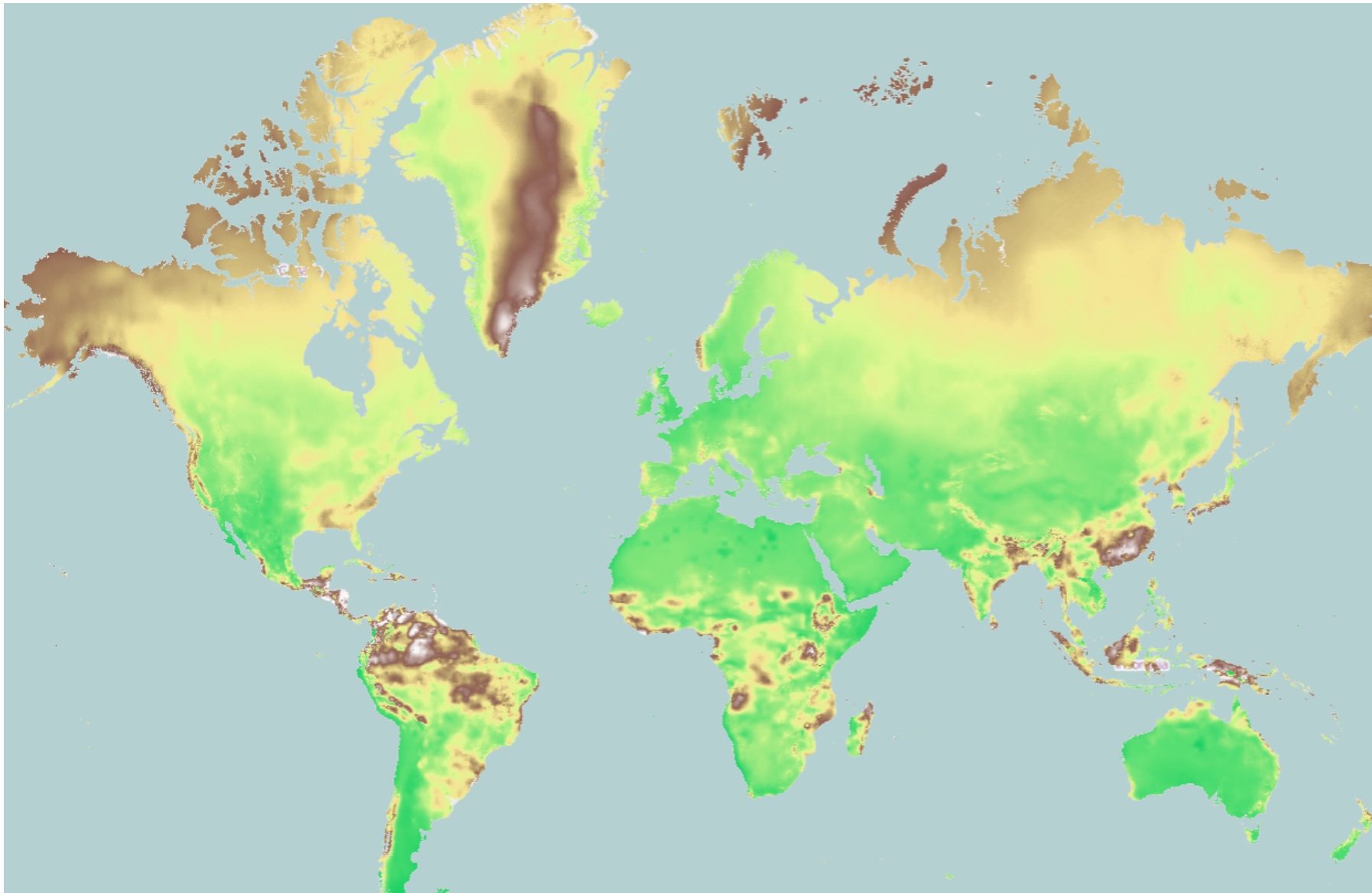


Change in land cover patterns over conterminous U.S. 2001-2006

Change 3 of 5



Change 4 of 5



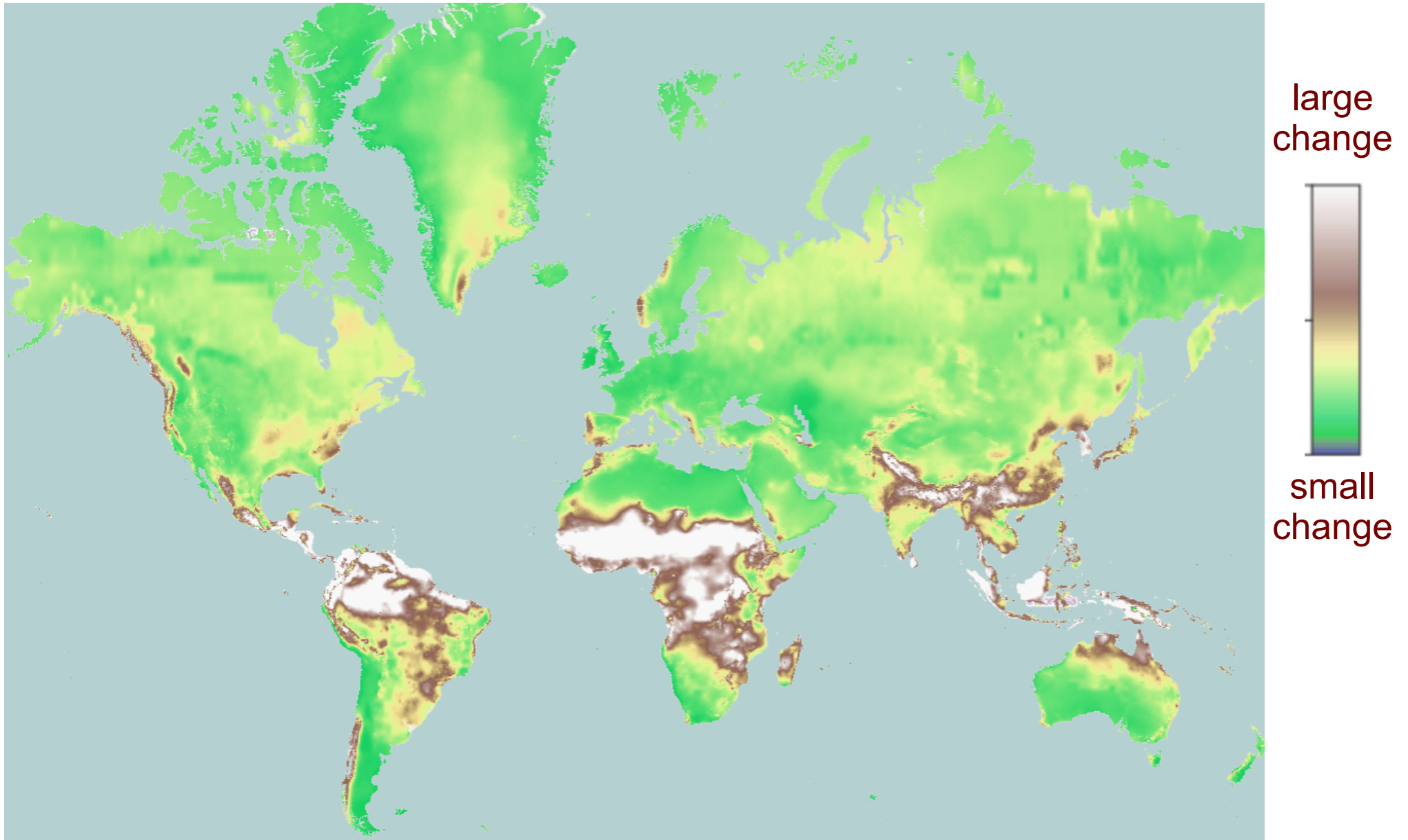
large
change



small
change

Climate change 2000 -2070

Search 5 of 5



Climate change -6000 -2000

Stand-alone version of GeoPAT

Present version of GeoPAT requires GRASS and (in most cases) Linux because GRASS needs to be compiled together with GeoPAT.

GeoPAT 2 is GRASS-free. All computations can be performed in terminal mode and exported to GIS software of choice (ArcGIS, QGIS, etc)

GeoPAT 2 will be provided as source code and as executable for Linux and Windows.

We have already converted several GeoPAT modules GRASS environment to stand-alone and demonstrated to work on Windows.

GeoPAT 2 will be open and free software

Summary

GeoPAT fills a niche devoted to analysis of large rasters (starting with GeoPAT 2 they don't need to be categorical).

Public data:

1. Land cover (NLCD, GLC30, GlobCover, CORINE, EOSD)
2. Topography (NED, SRTM)
3. Croplands (USDA CropScape)
4. Urban Structure Types (UST) (National Map)

Applications:

1. Ecology (delineation of ecoregions)
2. Forestry (conservation planning and management)
3. Agriculture (identify spatio-temporal patterns of usage of U.S. croplands)
4. Climate (climate change)

Roadmap for the next 12 months

GeoPAT:

1. Finish development and release GeoPAT 2 for GRASS
2. Finish development and release the stand-alone GeoPAT 2
3. Finish development and release GeoPAT 2 optimized for Xeon Phi

Online applications:

1. Finish TerraEx

Testing GeoPAT on public data

1. Calculate and validate regionalization of US into physiographic units
2. Calculate and validate regionalization of US into landscape types
3. Validate utility of GeoPAT for delineation of UST in American cities