



Demonstration of High-frequency Airborne Microwave and Millimeter-Wave Radiometer (HAMMR) to Improve Spatial Resolution of Wet-Tropospheric Path Delay Measurements for Coastal and Inland Water Altimetry

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2014



Surface Water and Ocean **Topography (SWOT) Mission**



- NASA/CNES/CSA Joint Mission from NRC Earth Science Decadal Survey Mission underway and planned for launch in Oct. 2020.
- Enhances capability and continues 22 years of high-precision sea level & surface topography measurements
- To make the first global survey of Earth's surface water, observe fine details of the ocean's surface topography, and measure how water bodies change over time
- Nadir altimeter and radiometer for wet-tropospheric correction
- Ka-band Radar Interferometer (KaRIn) with 120-km wide swath over 140 km Reising et al., B2P6







• NASA's Earth Science Focus Areas:

- Water & Energy Cycle
- Climate Variability and Change

Oceanography Objectives:

- Characterize ocean mesoscale and sub-mesoscale circulation at horizontal resolution of 15 km with order of 1 cm height precision
 - Kinetic energy / Heat and carbon air-sea fluxes
 - Climate change and ocean circulation
 - Coastal and internal tides

Hydrology Objectives:

- To provide global height measurements of inland surface water bodies with area greater than 250 m² and rivers of width greater than 100 m with 10 cm height precision
- To measure change in global water storage in inland water bodies and river discharge on sub-monthly to annual time scales

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Scientific Motivation



- Radar altimeter missions include nadir-viewing 18-34 GHz microwave radiometers to measure wet-tropospheric path delay. These radiometers, including the baseline for Jason Continuity of Service (CS) and SWOT, cannot provide sufficient measurements in coastal areas and over land.
- Error due to land incursion is unacceptable within 30-40 km of the coastlines.
- A second, high-frequency radiometer is under consideration for possible inclusion on Jason-CS mission by EUMETSAT/ESA/CNES/NOAA/NASA.



- Wide-band, high-frequency window channels at 90, 130 and 168 GHz provide an optimal frequency set to improve coastal retrievals.
- We have developed new algorithms for retrieval over inland water using ratios of window channels without the need for *a-priori* data.

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Wet Path Delay Retrieval in Coastal Zones



- A hybrid Bayesian retrieval algorithm, coupled with a high-resolution WRF model, was developed and applied to simulated brightness temperatures.
- Addition of high-frequency channels yielded wet path delay retrieval error of < 8 mm to within about 5 km of the coastlines.





Application of Wet-Path Delay Retrieval Algorithm to GPM Microwave Imager



- The Global Precipitation Measurement Microwave Imager (GMI) has 18.7-37.0 GHz channels and also a high-resolution 90 GHz channel.
- GMI data used to evaluate algorithm performance in real atmospheres.
- Path delay computed from GMI low-frequency (18-37 GHz) channels.
- High-frequency (HF) coastal extrapolation algorithm applied to 90 GHz channel.
- 500 km segments extracted and used to evaluate algorithm.
 - 400 km used to dynamically train HF algorithm.
 - HF algorithm then applied to last 100 km and compared to low-frequency PD.



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High-Frequency Algorithm Performance using GPM Microwave Imager



- HF Extrapolation algorithm using GMI 90 GHz channel compared to using last valid PD value to the coast
- Computed statistics for a large number of realizations, encompassing various atmospheric conditions
- Assuming a low-frequency radiometer that is contaminated at 50 km from the coast, HF algorithm decreases error from 10 mm to 4 mm.





Understanding Swath-Scale Water Vapor Variability



SWOT baseline mission includes only nadir radiometer, highlighting the need to characterize small-scale water vapor variability to understand errors across the 120-km wide swath over 140 km.



Model path delay fields from Weather Research and Forecasting (WRF) model (cm)



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High-Frequency Airborne Microwave and mm-Wave Radiometer



Under support from NASA ESTO's Instrument Incubator Program 2010, we have developed and built the Highfrequency Airborne Microwave and Millimeter-wave Radiometer (HAMMR) operating from 18.7 to 183 GHz, and demonstrated its operation on a Twin Otter aircraft. HAMMR will:

- 1. Provide high-resolution measurements of wet-path delay from aircraft on the order of 100-m scales
- 2. Provide high-frequency millimeter-wave brightness temperatures to test algorithms to extend wettropospheric path delay correction closer to the world's coastlines and explore the potential over inland water
- 3. Demonstrate high-frequency millimeter-wave radiometers that can be directly integrated into future altimetry space missions
- 4. Provide an airborne calibration and validation instrument in support of the SWOT mission, complementary to JPL's AirSWOT Reising et al., B2P6 ESTF 2014, Leesburg, VA USA



Scan

Twin Otter Deployment:

- Altitude: 3 km
- Swath Width: 6 km
- Scan Rate: 60 rpm



Wide-Band Airborne Radiometer System Block Diagram



- Low-frequency microwave channels - 18.7, 23.8 and 34.0 GHz High-frequency millimeter-wave window channels - 90, 130 and 168 GHz - High-frequency mm-wave sounding channels - ASIC analog spectrometer with 8 Analog bands each near 118 and 183 GHz Analog and digital back-end w/ FPGA - Radiometer signal conditioning, integration & sampling Timing of Dicke switching and -Encoder internal calibration Scanning Motor Temperature control and monitoring
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Green: CSU; Red: JPL; Blue: NCAR

Wide-Band Airborne Radiometer System Design

Knowledge to Go Places







Three Feed Horn Antennas for Three Frequency Channel Sets



High-Frequency Millimeter H wave Sounding Channels (118 and 183 GHz)

High-Frequency Millimeter Wave Window Channels (90, 130 and 168 GHz) Low-Frequency Microwave channels (18.7, 23.8 and 34 GHz)



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Sampling and Data Rates



Sampling rates were chosen to ensure contiguous along-track sampling using Twin Otter aircraft specifications of 3 km altitude (unpressurized), 33 m/s ground speed, 60 rpm scan rate, and scene observations from -45° to 45° incidence angle.



	Microwave Radiometers (Quasi-H & V)	mm-Wave Window Channels	mm-Wave Sounding Channels
Number of Channels	6	3	16
Sample Rate	5 kHz	10 kHz	370 Hz
Footprint Dimensions at highest frequency & maximum scan angle	159 x 224 m	25 x 36 m	50 x 70 m
Swath Width	6 km	6 km	6 km
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Footprint of low-frequency microwave radiometers (18-34 GHz)

Footprint of high-frequency mm-wave radiometers (90-175 GHz)

Footprint of 118 and 183 GHz sounding radiometers



High-Frequency Millimeter-Wave Window Channels





- fabricated for ESTO Advanced Component Technology 2008 WR-10 (90 GHz)
 - Multi-chip modules with integrated internal calibration
 - ow-mass, low-power direct-detection architecture

Waveguide

Port

WR-8 (130 GHz) Waveguide

Port



High-frequency Millimeter-wave Radiometers at 90, 130 & 168 GHz





Tri-Frequency Feed Horn from ESTO ACT-08

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HAMMR Integration in Twin Otter Grand Junction, CO, July 8, 2014





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HAMMR Integration in Twin Otter Grand Junction, CO, July 8, 2014





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Summary of HAMMR Flights from Grand Junction, Colorado, July 2014



- Successful completion of 14 flight hours over 3 days
 - First day over Blue Mesa Reservoir, Colorado
 - Second and third days over Lake Powell, Utah and Arizona
- HAMMR instrument and subsystems worked well
- Physical temperatures throughout radiometer system were stable
- HAMMR radiometer channel subsystems performed very well
- Cross-track scanning was very stable; aerodynamics and turbulence were not a problem
- Ambient and LN₂ calibration was performed using an external target before and after each flight

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HAMMR Flights over Lake Powell, Utah and Arizona, July 10-11, 2014





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Flight Lines over Lake Powell, Utah and Arizona, July 10-11, 2014





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Low-Frequency Microwave Radiometer Measurements





Measurements were performed over Lake Powell, Utah on July 11, 2014.

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High-Frequency Millimeter-wave Radiometer Measurements





Measurements were performed over Lake Powell, Utah on July 11, 2014.

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- Improve calibration of L1a antenna temperatures from microwave and mm-wave window channels using Dicke matched load and internal noise sources (two per mm-wave window channel)
- Complete data processor to convert L1a antenna temperatures to L1b geolocated brightness temperatures by accounting for the antenna pattern, location and aircraft attitude
- Retrieve microwave channel wet-path delay using baseline algorithms and use to train mm-wave window channel wet-path delay algorithm to extrapolate retrievals to land. Finally, compare mm-wave retrievals with microwave channel retrievals to determine precision of high-resolution wet-tropospheric correction.
- Determine statistics of small-scale water vapor spatial variation during U.S. west coast campaign, including effects of grid resolution
- Assess added value of humidity and temperature sounding channels

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Preliminary HAMMR Flight Plan along Southern California Coast



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Preliminary HAMMR Flight Plan for Oregon & Washington Coasts





Flight Campaign Goals:

- Measure water vapor variability in the coastal zone and over inland water
- Measure under a wide variety of weather conditions over land & ocean
- Perform on-shore and off-shore flight segments to detect any scan bias
- Limited to max. altitude of 10,000 ft MSL in unpressurized cabin and a maximum of 8 flight hours per day
- Total of 45 flight hours, including ferry flights between Grand Junction, Colorado, Camarillo, California, and Eugene, Oregon

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Tropospheric Water and Cloud ICE (TWICE) IIP-13



• Objectives:

- Develop wide-band millimeter and submillimeter wave radiometer to measure upper-tropospheric water vapor, cloud ice particle size distribution and water content at a variety of local times
- Demonstrate advancement of state of the art of sub-millimeter wave radiometers to InP HEMT MMIC LNA front ends up to 660 GHz
- Reduce size, mass and power consumption to enable deployment on a 6U CubeSat platform
- Frequency Channels:
 - Cloud ice particle sizing at window channels of 240, 310 and 660 GHz (dual-pol) using direction-detection radiometers.
 - Upper tropospheric water vapor sounding near 118 GHz, 183 GHz and 380 GHz with offsets up to 8 GHz, all based on an ASIC analog spectrometer developed for HAMMR.



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Summary



- Conventional altimeters with nadir-viewing 18-34 GHz microwave radiometers to measure wet-tropospheric path delay have limited accuracy within 30-40 km of land.
- The addition of high frequency (90-175 GHz) radiometers to ocean altimetry
 missions is expected to improve spatial resolution of wet-path delay retrievals near
 the coasts and enable retrievals over inland water.
- High-frequency Airborne Microwave and mm-Wave (18-183 GHz) Radiometer (HAMMR) was successfully demonstrated on a Twin Otter this July. HAMMR will:
 - Provide high-resolution measurements of spatial variability of tropospheric water vapor on 100-m scales from aircraft
 - Provide high-frequency millimeter-wave brightness temperature measurements to extend wet-tropospheric path delay correction closer to the world's coastlines and explore the potential over inland water
 - Demonstrate millimeter-wave radiometer technology that can be directly integrated into future altimetry space missions
 - Provide an airborne calibration and validation instrument in support of the SWOT and Jason-CS missions that is complementary to JPL's AirSWOT

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