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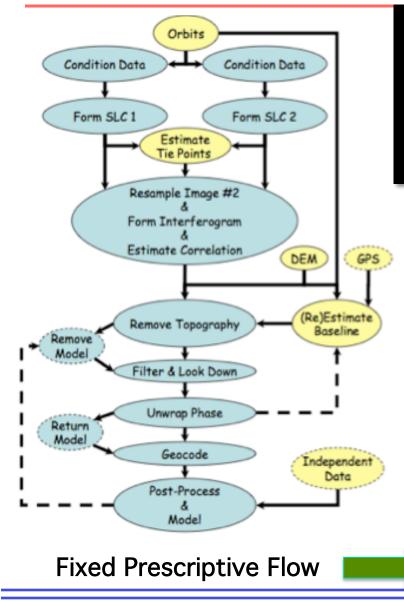
- Introduction
- Technology Description
- Functionality
- Part of the ARIA-MH Production System
- Core Technology in Earthkit and CESCRE cloud-based computing
- Baseline for proposed NISAR Algorithm Core
- Recently upgraded to support UAVSAR Interferometry and Polarimetry for Time-Series stacks
- Vision for ISCE architecture
  - What international missions it supports and how
  - How does it support the user community

Pre-decisional - for Planning and Discussion Purposes Only





#### Interferometric Synthetic Aperture Radar (InSAR) From Recipes to Reconfigurable Flow



Radar in space

/Users/parosen/Projects/CSK/hawaii> python3 >>> import isce

>>> from applications.insarApp import Insar

2014-10-18 17:47:51,008 - isce.insar - INFO -ISCE VERSION = 2.0.0\_201409, RELEASE\_SVN\_REVISION = 1612, RELEASE\_DATE = 20140918, CURRENT\_SVN\_REVISION = 1647

>>> a.rangeLooks = 4
>>> a.run()

Insar Application: Implements InSAR processing flow for a pair of scenes from sensor raw data to geocoded, flattened interferograms.

<sup>...</sup> Flexible "Sandbox" ISCE Flow

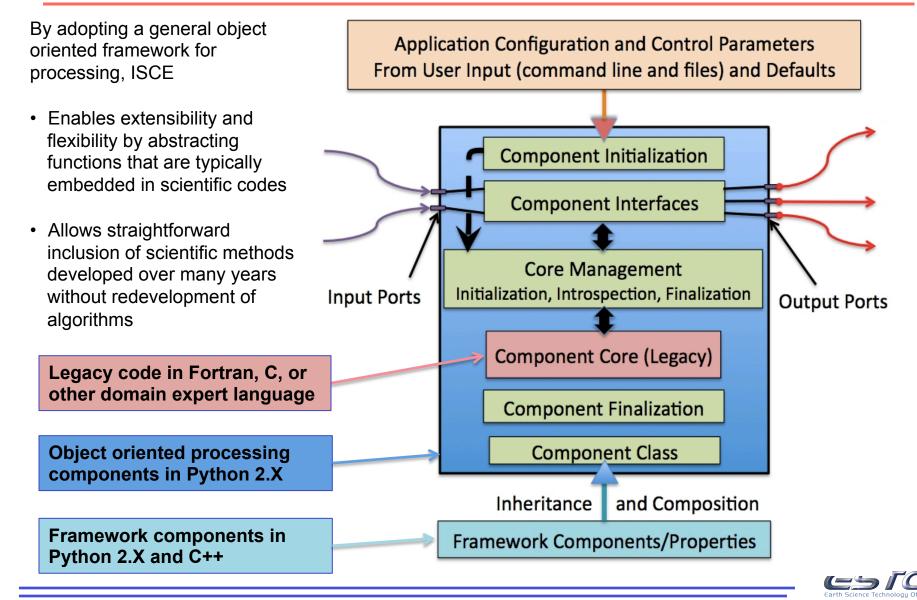




- Created accurate and fast algorithms based on GEOSAR and SRTM heritage
- Advantages of improved accuracy and speed:
  - Enable InSAR and time series methods with precise SLC alignment requirements
  - Straightforward merging SAR data with other types
  - Feasible processing of dozens of scenes by a desktop user
- Approach
  - Define a rigorous geometric framework tied to local spherical coordinate system
  - Adjust collection of images to a common reference trajectory
  - Condition data for ingestion in post-processing time-series applications such as GIAnT









- Object orientation using Python
- A common hierarchical structure for defining components and applications
- An Image API & I/O API to abstract access to data and metadata
- Runtime polymorphism through factory pattern creation of components
- Provenance through xml metadata and python *pickle* mechanisms

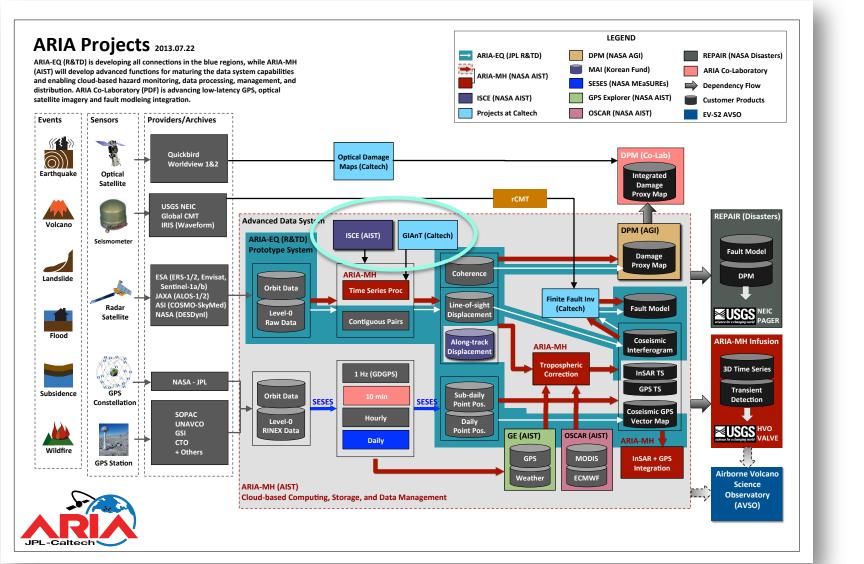




- Code supports strip mode data from
  - ERS-1, ERS-2, ENVISAT, RADARSAT-1, RADARSAT-2, Sentinel-1
  - JERS, ALOS-1, ALOS-2
  - TerraSAR-X, Cosmo-Skymed (CSK)
  - UAVSAR
- Unix/Linux build environment requires
  - gcc 4.7+, Python 3.3+, numpy, fftw 3.2, scons 2.0.1, motif
  - spiceypy (RadarSAT1 only)
  - gdal (RadarSAT2 only)
  - hdf5 (CSK only)
- UNAVCO is licensed to distribute the ISCE software to members of the WInSAR consortium
  - WInSAR members comprise a significant portion of the ISCE user base
  - WInSAR maintains a large database of InSAR raw data, as well as processing tools
- Individual research licenses can be provided by Caltech



### ISCE as the core of ARIA Advanced Rapid Imaging Analysis system

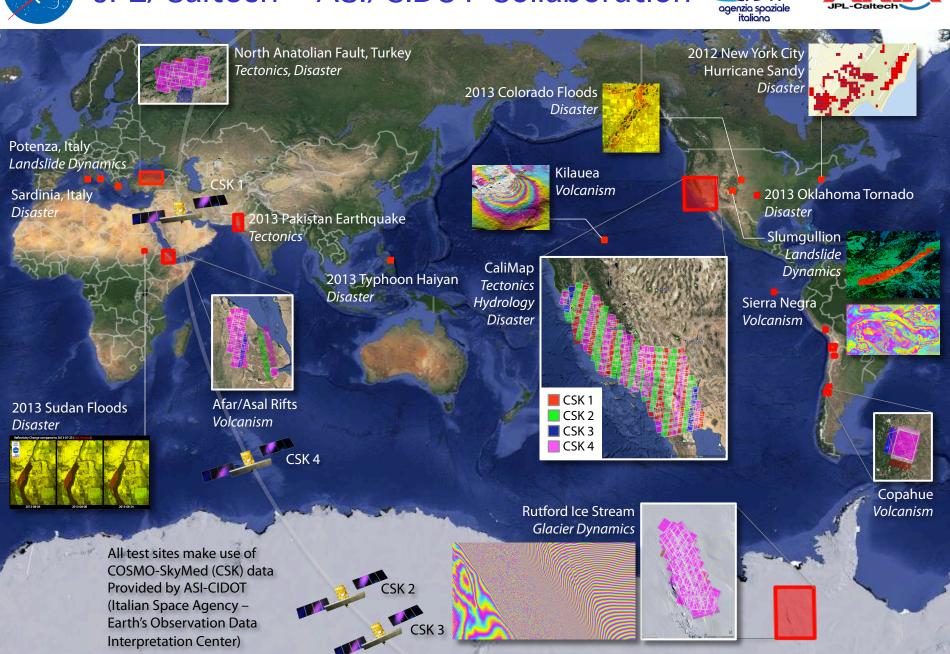




# JPL/Caltech – ASI/CIDOT Collaboration

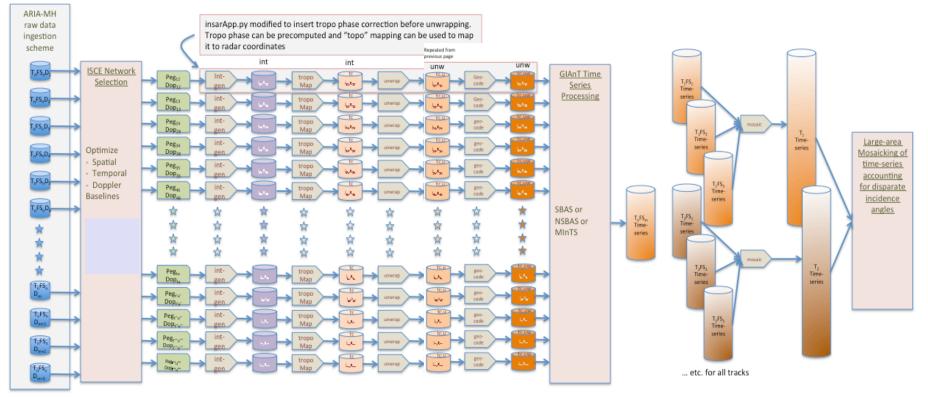


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## Automated InSAR Processing Architecture for Large Scale Analysis



ARIA data system uses

- InSAR Scientific Computing Environment (ISCE) software
- GIAnT software for time series analysis

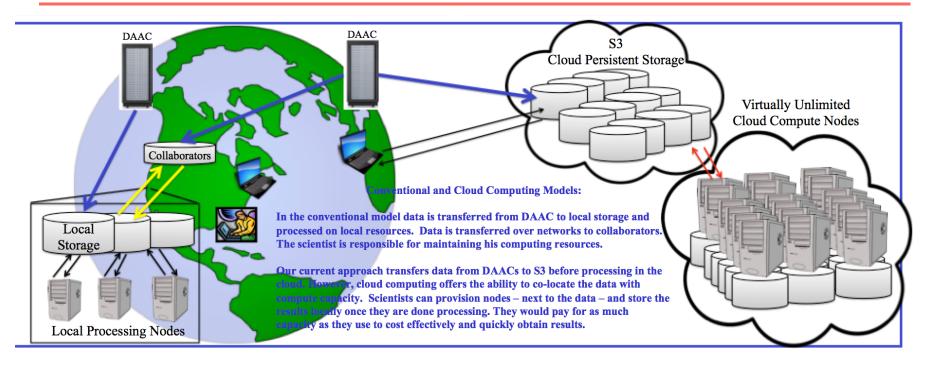
To generate

- Interferograms
- Tropospheric corrected interferograms
- Velocity maps





### CESCRE – Cloud Enabled Scientific Collaborative Research Environment (Mark Powell, PI)



- CESCRE developed a framework for processing data and sharing results on the Amazon cloud
- ISCE was the fundamental test environment for CESCRE collaboration
- CESCRE allows a user to sit at their laptop and harness the full power of the amazon cloud





#### Earthkit Tutorials for ISCE/GIAnT Mark Powell, PI

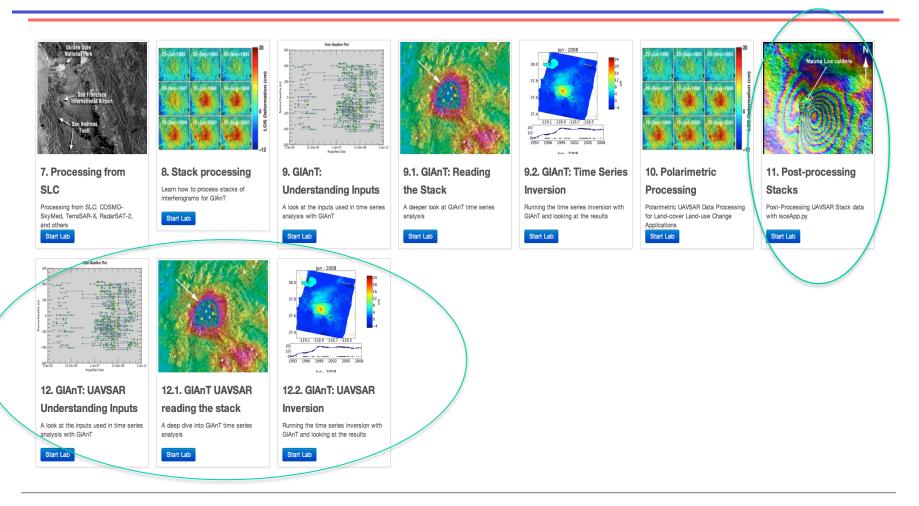
EarthKit Lab beta Home egurrola 12.2. GIAnT: UAVSAR Inversion Launch Mauna Loa calder EARTHKIT EarthKit: Getting 1. Getting started with 1.1 Number formats in 3.1. Processing ALOS 3.1.1. ALOS input file 2. Using MDX 3. Using insarApp.py ISCE ISCE PALSAR Started Using the visualization tool MDX to Processing Interferometric Data Sets examples analyze interferograms using insarApp.py - Overview Start here to learn how to use the Getting started with ISCE hands-on A reference document for ISCE number Learn to generate interferograms from A deeper look into authoring input for EarthKit self-led lab system ALOS PALSAR data ALOS data processing formats Start Lab AVCO, SAR Arshiv 20061018 20061213 20070118 20070305 20070605 2007-1206 20060121 **3.2 Files and Formats** 3.3 insarApp options 3.4. SAR Data Access 4. Processing ERS 4.1. ERS input file 5. Processing EnviSAT 6. Processing COSMO-SkyMed Understanding output files and formats Exploring the insarApp.py processing Running SSARA to query and download Learn to generate interferograms from examples Learn to generate interferograms from option space data ERS data EnviSAT data A deeper look into authoring input for Learn to generate interferograms from COSMO-SkyMed data ERS data processing Start Lab Start Lab Start Lab Start Lab Start Lab Start Lab Start Lab

• Extensive, cloud-based, interactive tutorials for learning about ISCE and GIAnT





# Earthkit Tutorials for ISCE/GIAnT



Including new modules for UAVSAR stack processing





# Earthkit Tutorials for ISCE/GIAnT

1/6 -

EarthKit Lab beta Home

#### 11. Post-processing Stacks

Remote Desktop SSH Shut down

egurrola

#### 1. Post-Processing UAVSAR Stack data with isceApp.py

In this lab, you will learn how to process UAVSAR Stack data, while learning about the ISCE application isceApp.py. Previous labs have used the application insarApp.py to process pairs of raw or single look complex data acquired on two different dates using spaceborne sensors into interferograms and geocoded products. In this lab we will work with the application isceApp.py to post-process several data sets from the same flight track acquired at different times with the UAVSAR radar flown on an airplane. The data downloaded from the UAVSAR website have already been processed to single look complex images by the UAVSAR team. Post-processing includes the following steps: forming interferograms from the slc data, removing topographic phase, filtering, unwrapping, and geocoding.

To get started change directory to the /data/lab11 directory (click the "Launch" button if you haven't already done so),

> cd /data/lab11

Take a look at the directory contents with the "Is -I" command,

#### > ls -1

demLat\_N38\_N39\_Lon\_W123\_W121.dem.wgs84.xml incoming -> /data/sites/Napa\_uavsar\_stack/incoming isceApp.xml precooked -> /data/sites/Napa\_uavsar\_stack/ SanAnd\_05510\_01\_BC.dop -> incoming/SanAnd\_05510\_01\_BC.dop SanAnd\_05510\_12128\_000\_121105\_L090HH\_01\_BC.ann -> incoming/SanAnd\_05510\_12128\_000\_121105\_L090HH\_01\_BC.sl\_1x1.slc -> incoming/SanAnd\_05510\_12128\_000\_121105\_L090HH\_01\_BC\_sl\_1x1.slc SanAnd\_05510\_13089\_001\_130508\_L090HH\_01\_BC.ann -> incoming/SanAnd\_05510\_13089\_001\_130508\_L090HH\_01\_BC.ann SanAnd\_05510\_13089\_001\_130508\_L090HH\_01\_BC.ann

#### puts.NUMBER AZIMUTH LOOKS = 16 runGeocode.uav10\_uav11\_hh../uav10\_uav11/uav10\_uav11\_hh.filt\_topophase.unw.in puts.MAXIMUM LONGITUDE = -121.88182067871094 \*\*\*\*\*\* 2014-10-28 18:55:52.321 - isce.isceProc.runGeocode - INFO -\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\* runGeocode.uav10\_uav11\_hh../uav10\_uav11/uav10\_uav11\_hh.filt\_topophase.un w - Outputs runGeocode.uav10\_uav11\_hh../uav10\_uav11/uav10\_uav11\_hh.filt\_topophase.unw.ou runGeocode.uav10\_\_uav11\_hh../uav10\_\_uav11/uav10\_\_uav11\_hh.filt\_topophase.unw.ou tputs.MINIMUM\_GE0\_LONGITUDE = -122.4080555555555 runGeocode.uav10 uav11 hh../uav10 uav11/uav10 uav11 hh.filt topophase.unw.ou tputs.LATITUDE SPACING = -0.00027777777777777778 runGeocode.uav10 uav11 hh../uav10 uav11/uav10 uav11 hh.filt topophase.unw.ou tputs.MAXIMUM GEO LATITUDE = 38.071388888888888 runGeocode.uav10 uav11 hh../uav10 uav11/uav10 uav11 hh.filt topophase.unw.ou tputs.MAXIMUM GEO LONGITUDE = -121.881666666666667 runGeocode.uav10\_uav11\_hh../uav10\_uav11/uav10\_uav11\_hh.filt\_topophase.unw.ou tputs.GE0 LENGTH = 1408runGeocode.uav10 uav11 hh../uav10 uav11/uav10 uav11 hh.filt topophase.unw.ou tputs.MINIMUM\_GE0\_LATITUDE = 38.4622222222222222 runGeocode.uav10\_\_uav11\_hh../uav10\_\_uav11/uav10\_\_uav11\_hh.filt\_topophase.unw.ou tputs.GEO WIDTH = 1896 \*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\* >

- Guided training through browser interface
  - Integrated step-by-step instructions and a Unix command line prompt to play with code and data.
  - No installation of code and software dependencies





## **UAVSAR Enhancements for ISCE**

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	UAVSAR Uninhabited Aerial Vehicle Synt	hetic Aperture Radar			
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ESTO supported enhancements in ISCE to enable scientists to work with UAVSAR products:

- post-process SLC images (provided by the UAVSAR project) into stacks of interferograms with options to filter, unwrap and geocode.
- enable scientists to use the ISCE framework and components to create work flows needed for their work with the data.





- The proposed NISAR mission plans to use the ARIA infrastructure for elastic computing of NISAR data to LOB (raw), L1 (Images), and L2 (interferometric and polarimetric) data levels
- ISCE will be augmented by the project to incorporate new functionality that would be needed for NISAR
  - Image focusing processor for the proposed NISAR mission
  - Calibration/Validation tools
  - Science algorithms for biomass, deformation, time-series analysis, and mosaicking
  - Integrated tutorials and training modules
- This functionality will be available to individual scientists on their local computing devices or through cloud services

Pre-decisional - for Planning and Discussion Purposes Only





- The ISCE framework has been designed with flexibility and extensibility that can work in a variety of contexts.
- ISCE can support the community at many levels
  - Individual users working on their laptop or local computing system
  - Users interacting with the cloud through VMs and staging methods for data and processor deployments
  - On-demand processing through web-based queries to a central server
  - Project-sponsored code core for production of multi-petabyte data sets
- Coordinated development across these levels will ensure a robust, community vetted science tool for NASA science from ROSES to missions like the proposed NISAR

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