



Jet Propulsion Laboratory
California Institute of Technology



Boundary-Layer Humidity Sounding Using a G-Band Differential Absorption Radar

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Silver Spring, MD

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The Vapor In-Cloud Profiling Radar (VIPR, ESTO IIP-16)

Presenter: Richard Roy, JPL

**Coauthors: Matt Lebsock (PI), Ken Cooper, Jose V. Siles, Luis Millán,
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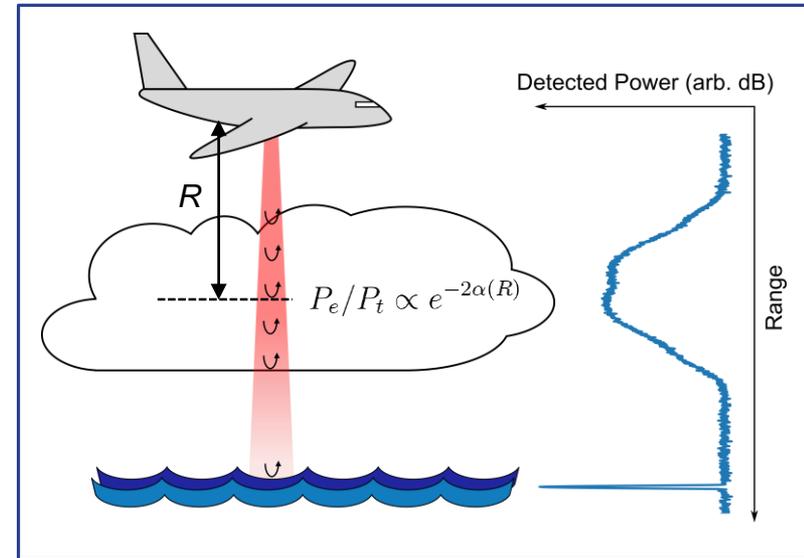
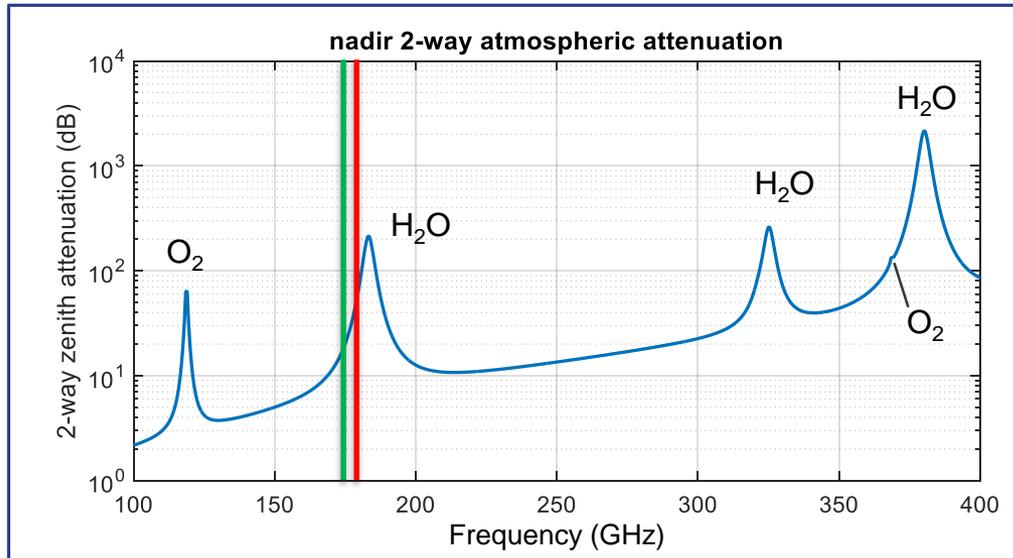


Problem:

- Existing remote sensing platforms have limited ability to retrieve *high-resolution, unbiased* water vapor profiles in the presence of clouds
- Problem recognized by NWP community (WMO, 2018):
“Critical atmospheric variables that are **not adequately measured** by current or planned systems are temperature and **humidity profiles** of adequate vertical resolution **in cloudy areas.**”

Proposed solution:

- Utilize range-resolved radar signal *and* frequency-dependent attenuation on flank of 183 GHz water vapor absorption line, so-called *differential absorption radar* (DAR)
- Microwave analog of differential absorption lidar (DIAL) – but can measure inside clouds (complementary observations)
- Langley - prototype pressure sounder using O₂ differential absorption, no ranging [1]



- Differential reflectivity between two closely spaced frequencies proportional to absorbing gas density (integrated)

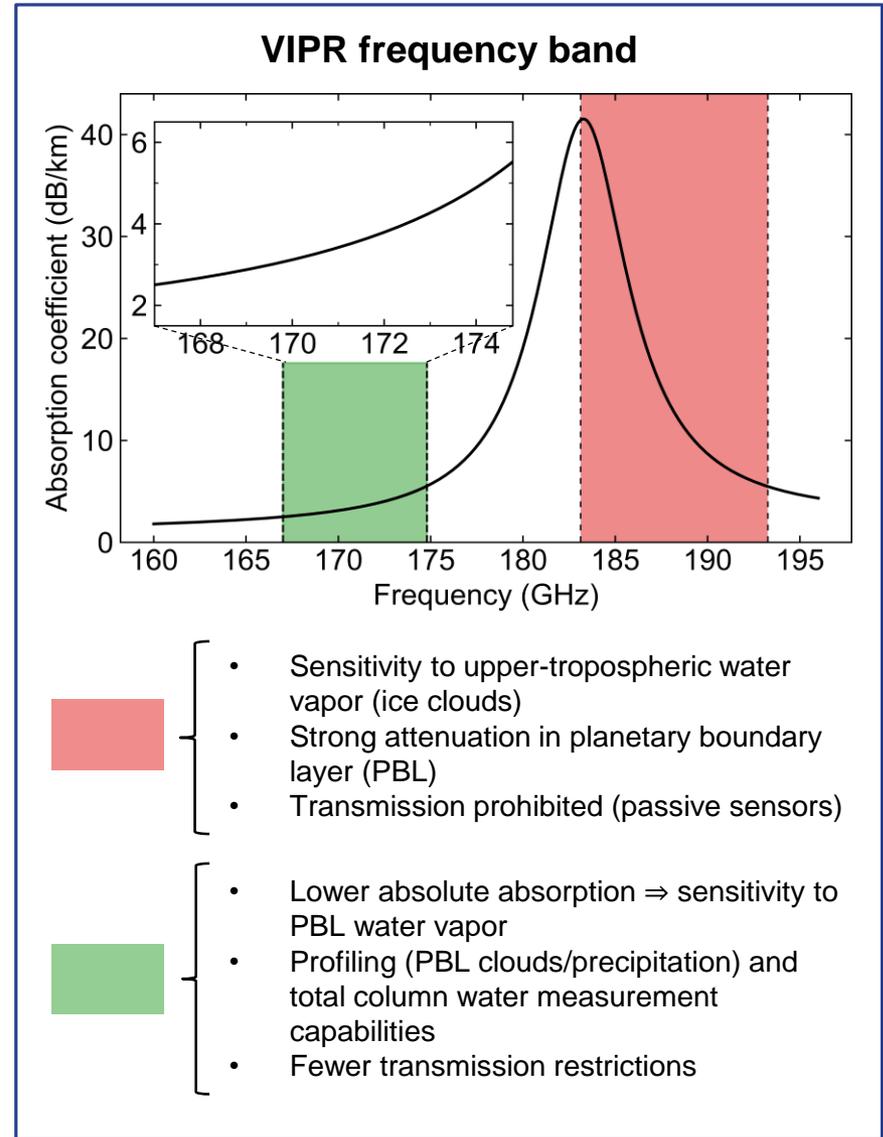
$$\text{dBZ}(r, f_1) - \text{dBZ}(r, f_2) \propto \int_0^r \rho_{\text{gas}}(r') dr'$$

- *Important assumption*: Reflectivity and extinction from hydrometeors independent of frequency
- Frequency dependence from hardware cancels out (common mode)
- Airborne platform \Rightarrow Surface echoes (total column water)



VIPR

- IIP-16 (PI: Matt Lebsock)
- Entry TRL = 3, exit TRL = 6
- Tunable across 167 to 174.8 GHz band
- Simultaneous cloud/vapor sounding
- Targets boundary layer clouds/precipitation and total column water vapor
- Demonstration flights on Twin Otter in 2019





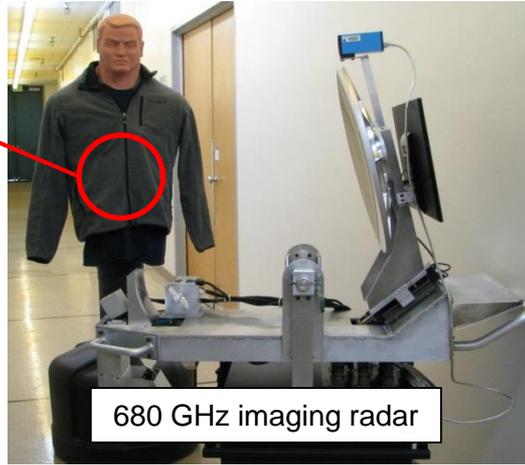
Targeted Observable	Science/Applications Summary	Candidate Measurement Approach	Designated	Explorer	Incubation
→ Clouds, Convection, and Precipitation	Coupled cloud-precipitation state and dynamics for monitoring global hydrological cycle and understanding contributing processes including cloud feedback	Radar(s), with multi-frequency passive microwave and sub-mm radiometer	X		
Atmospheric Winds	3D winds in troposphere/PBL for transport of pollutants/carbon/aerosol and water vapor, wind energy, cloud dynamics and convection, and large-scale circulation	Active sensing (lidar, radar, scatterometer); or passive imagery or radiometry-based atmos. motion vectors (AMVs) tracking; or lidar**		X	X
→ Planetary Boundary Layer	Diurnal 3D PBL thermodynamic properties and 2D PBL structure to understand the impact of PBL processes on weather and AQ through <u>high vertical and temporal profiling of PBL</u> temperature, <u>moisture</u> and heights	Microwave, hyperspectral IR sounder(s) (e.g., in geo or small sat constellation), GPS radio occultation for diurnal PBL temperature and humidity and heights; water vapor profiling DIAL lidar; and lidar** for PBL height			X
Surface Topography and Vegetation	High-resolution global topography including bare surface land topography ice topography, vegetation structure, and shallow water bathymetry	Radar; or lidar**			X



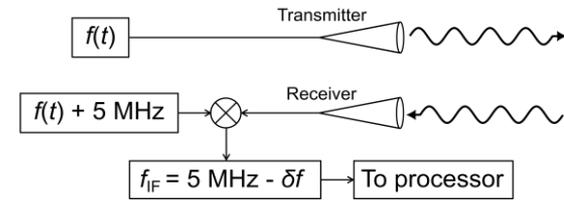
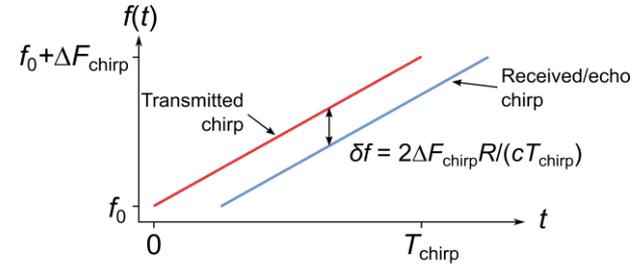
Frequency-modulated continuous-wave (FMCW) radar for security imaging



through-clothes detection

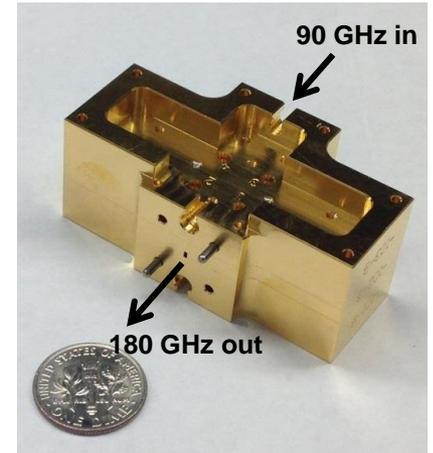
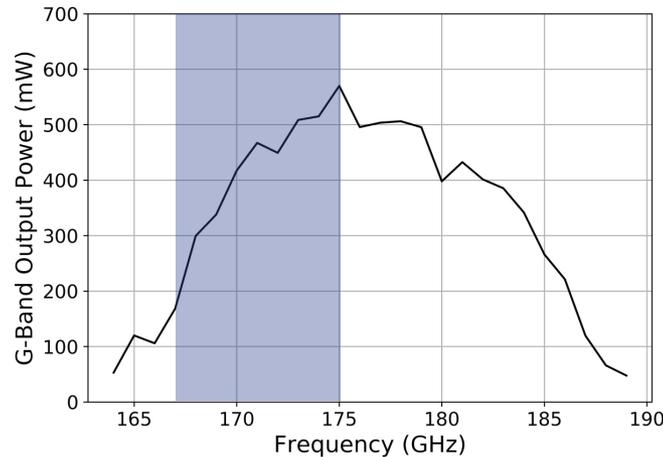


680 GHz imaging radar



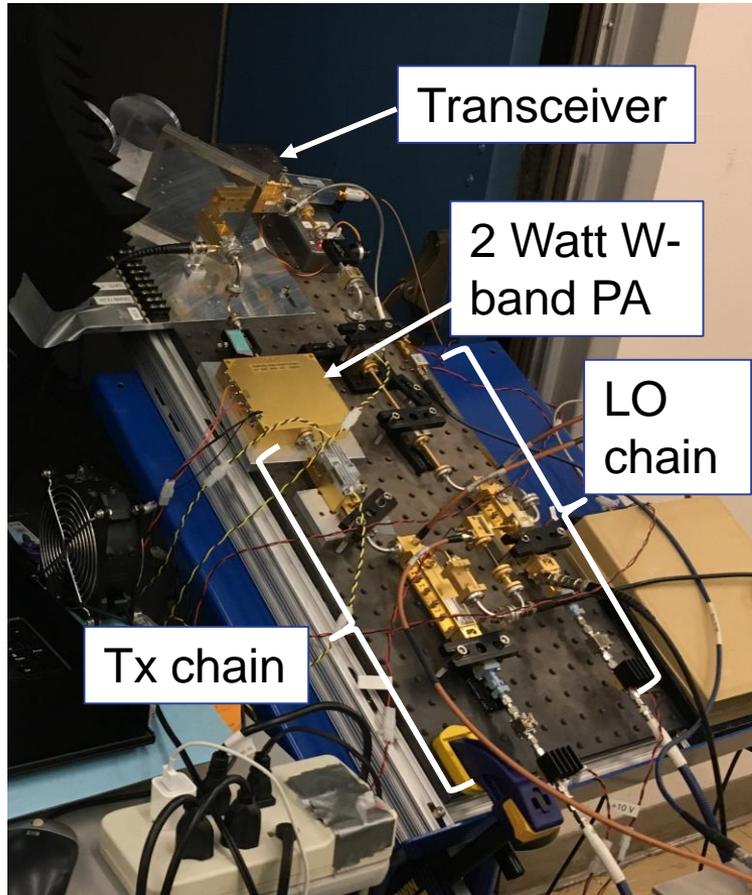
- Extensive THz FMCW radar R&D for security imaging applications
- ESTO funded effort for high-power solid-state sources near 183 GHz (ESTO ACT-13)
- State-of-the-art InP low-noise amplifiers developed for millimeter-wave radiometry and heterodyne spectroscopy

Record output power G-band sources

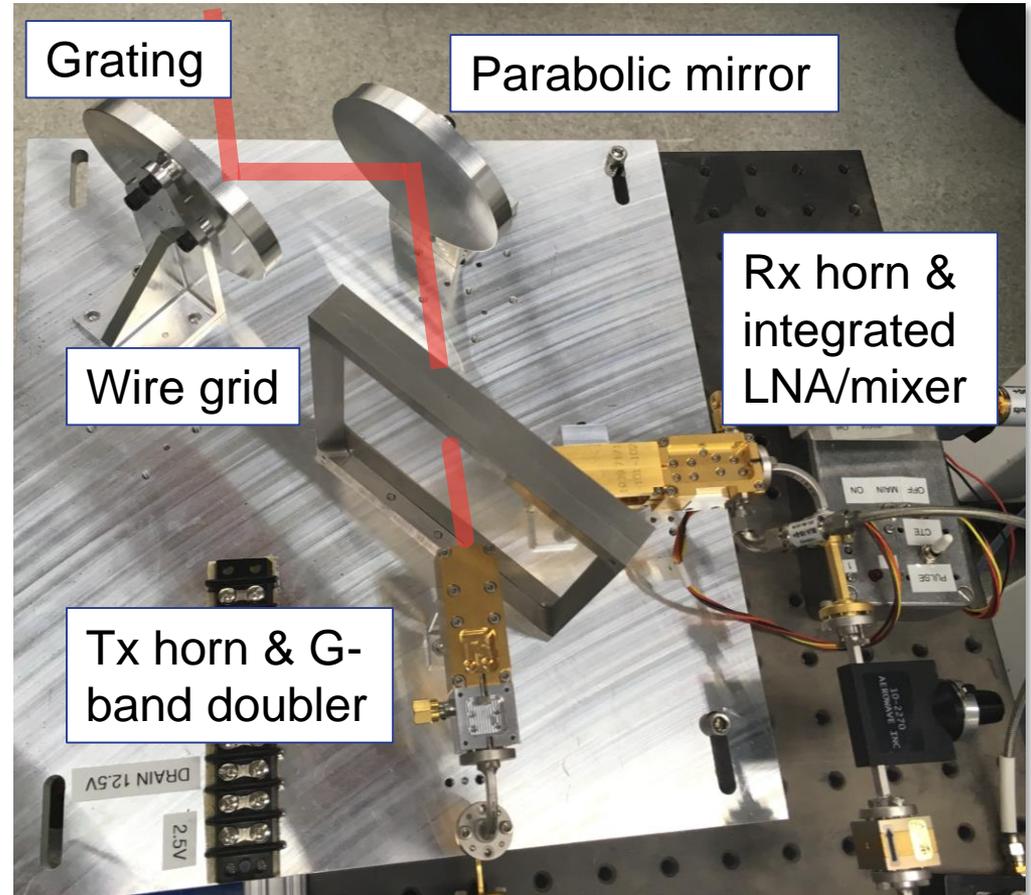




Radar front end



Transceiver

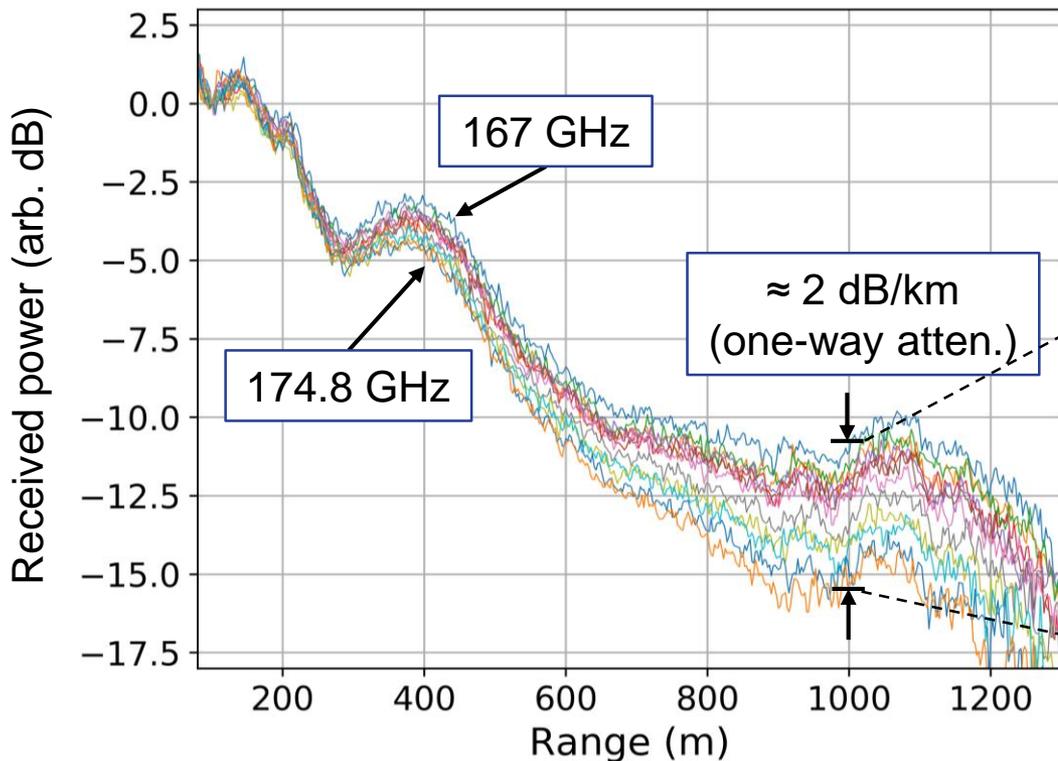


- 100 mW Tx power
 - 40 dB antenna gain
- } *Values for initial testing*



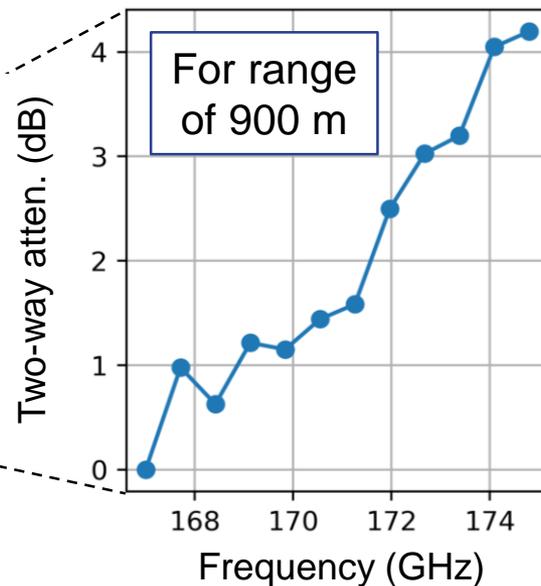
Precipitating clouds

Power spectra normalized to values at 100 m



Reflectivity

$$r^2 P_e(r, f) \propto Z(r) e^{-2\alpha(r, f)}$$





- Differential measurement derived from ratio of *radar echo power* at two different ranges:

$$\frac{P_e(r_2, f)}{P_e(r_1, f)} \propto e^{-2\alpha(r_1, r_2, f)}, \quad \alpha(r_1, r_2, f) \propto \int_{r_1}^{r_2} \rho(r') dr'$$

One-way optical depth

- But the power we detect is the sum of the echo power *plus* the background noise power:

$$P_d(r, f) = P_e(r, f) + P_n(r, f)$$

- Note:

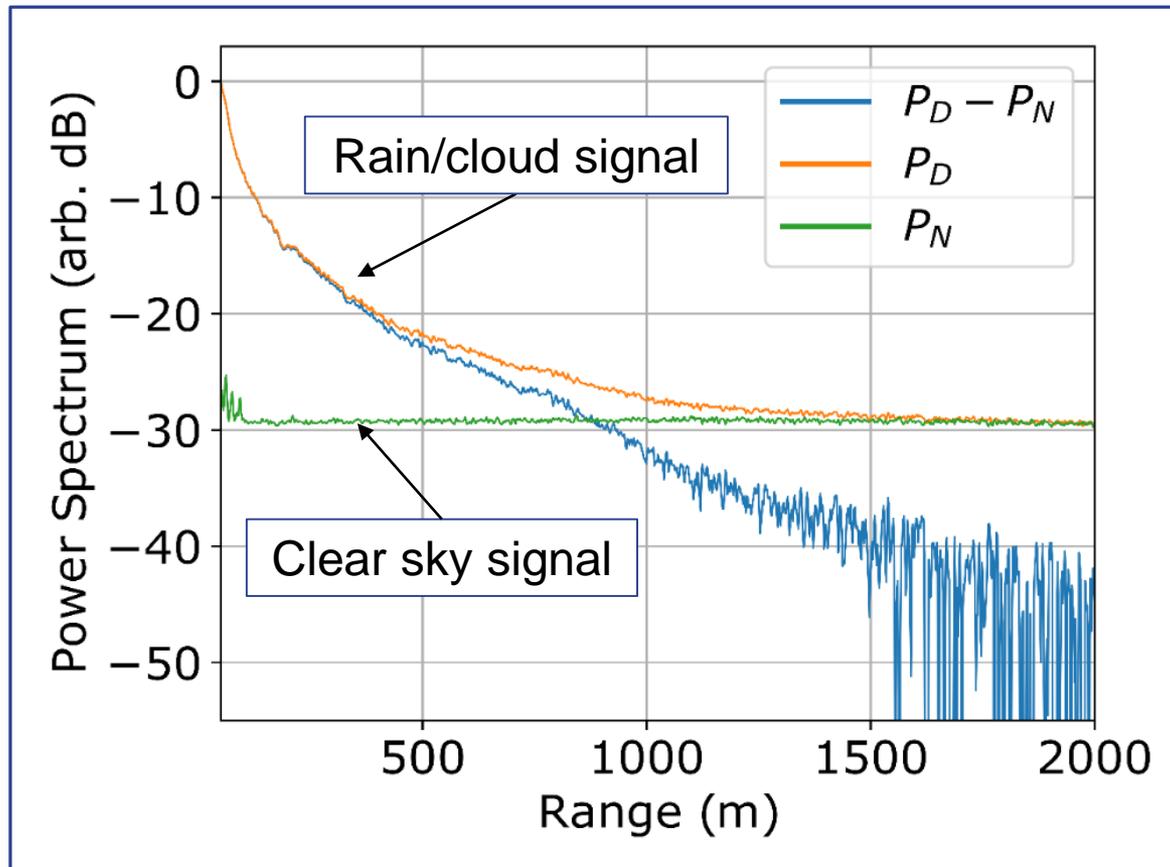
$$P_n(r, f) \neq \text{constant}$$

- Ripple in the radar IF spectrum
- Changing scene brightness temperature

⇒ have to acquire and subtract true background noise floor – otherwise clear low-humidity bias for low-SNR

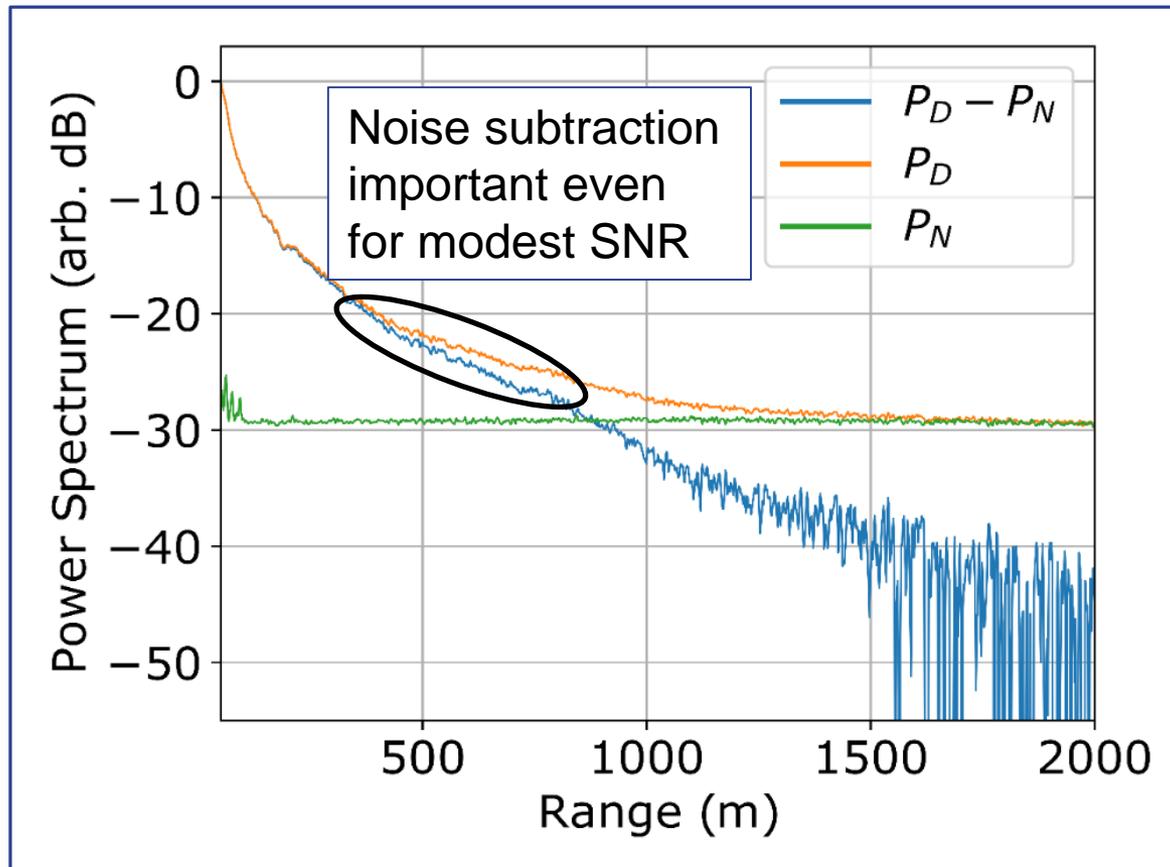


- Strategy 1:
 - Acquire radar spectrum with clouds/rain present
 - Wait for sky to clear and acquire background spectrum for subtraction



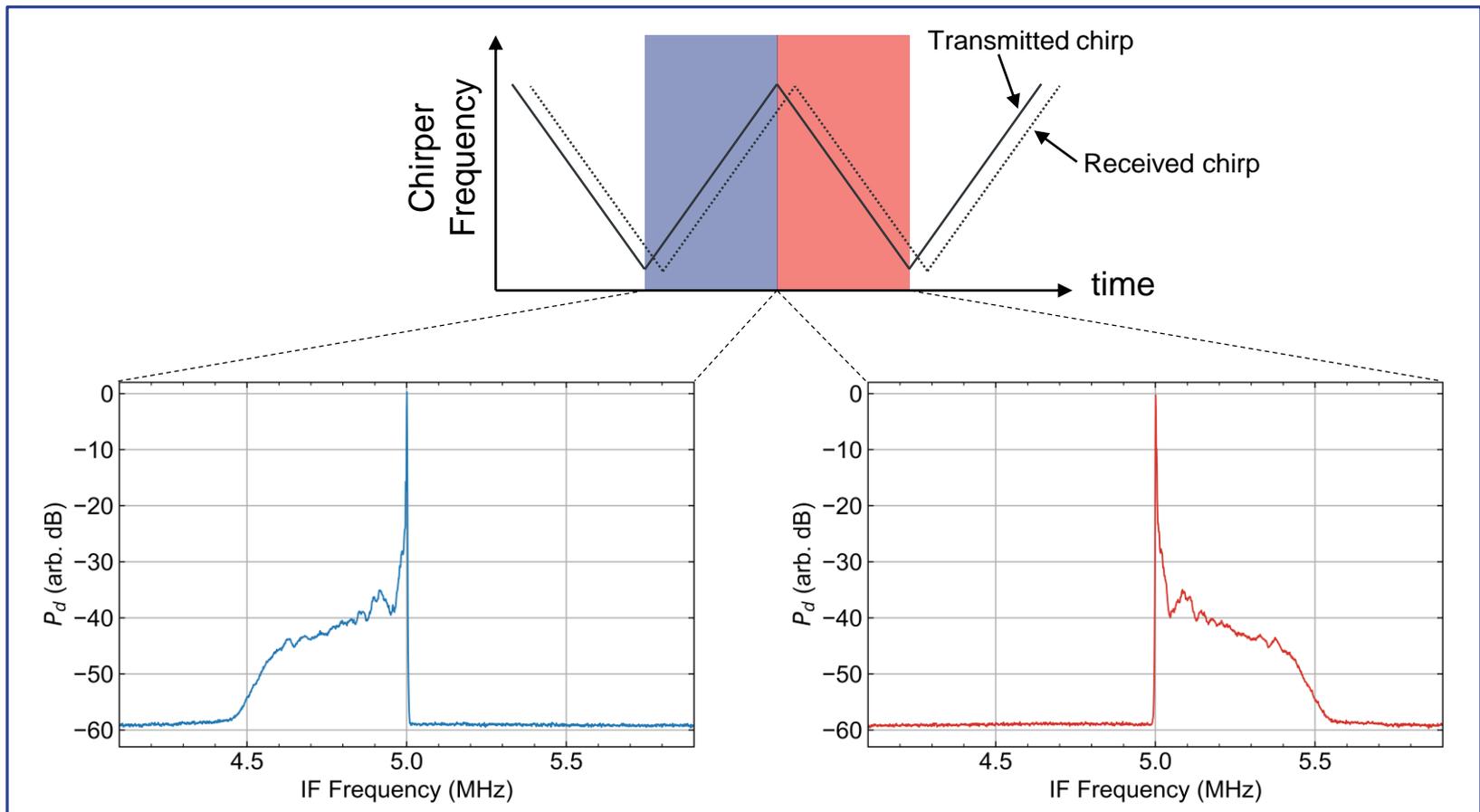


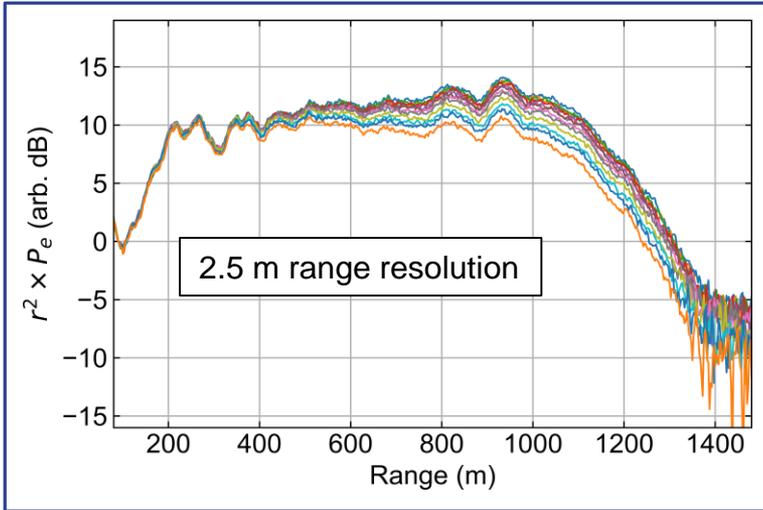
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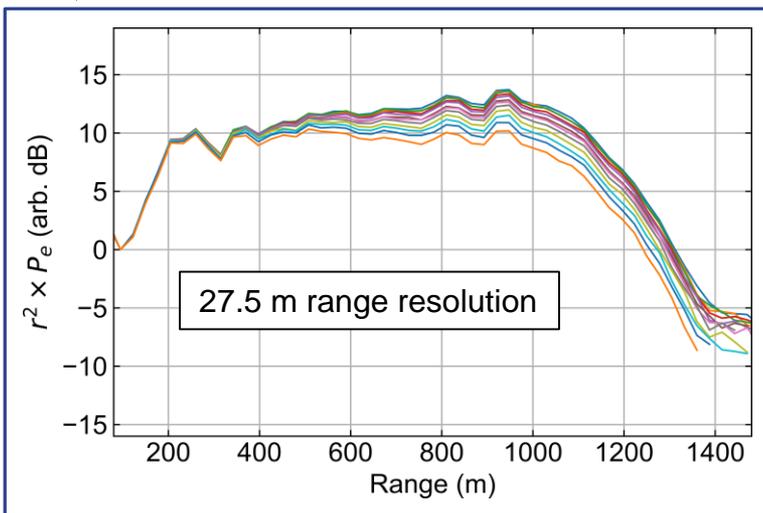


- Strategy 2:
 - Acquire cloud/rain signal spectrum **and** background noise floor simultaneously by using bidirectional chirp (triangle wave)

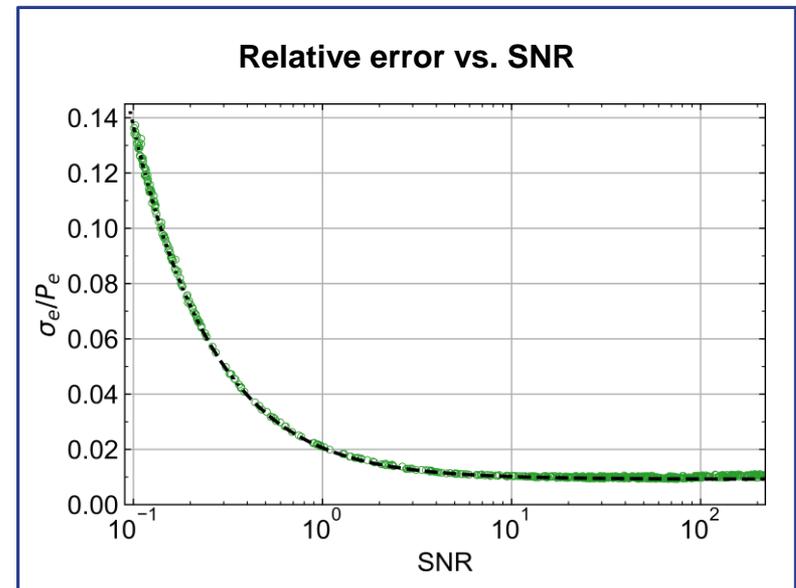




Bin (i.e. downsample) radar spectra by factor of 10 to reduce statistical uncertainty



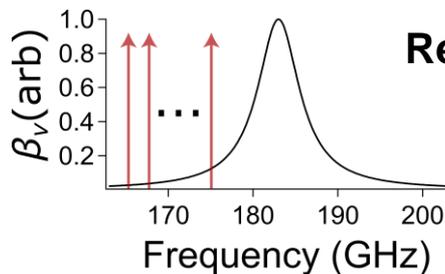
- Measurement error agrees very well with statistical model based on radar speckle noise



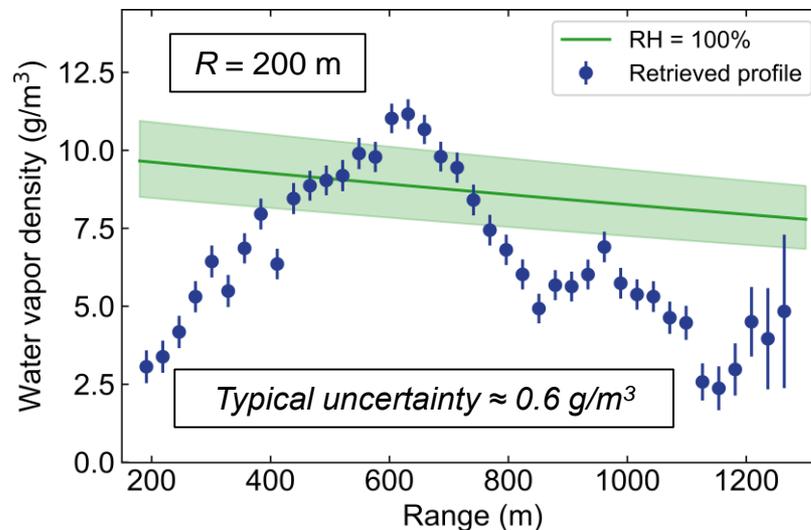
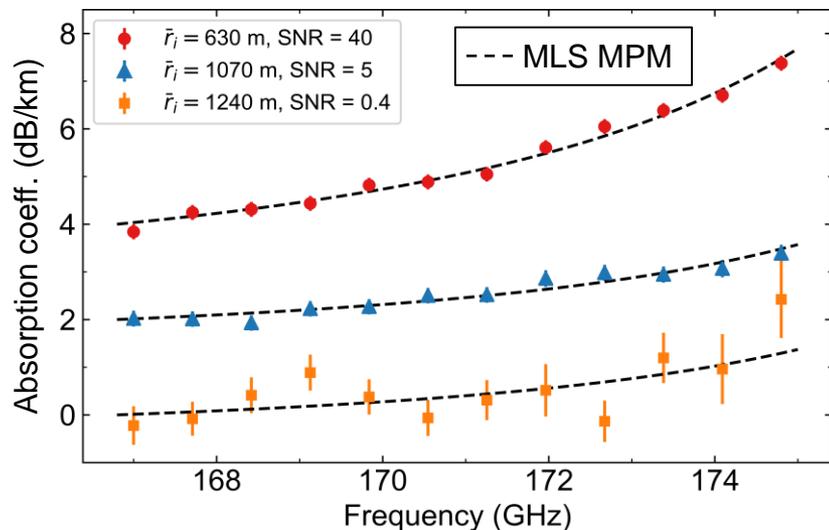
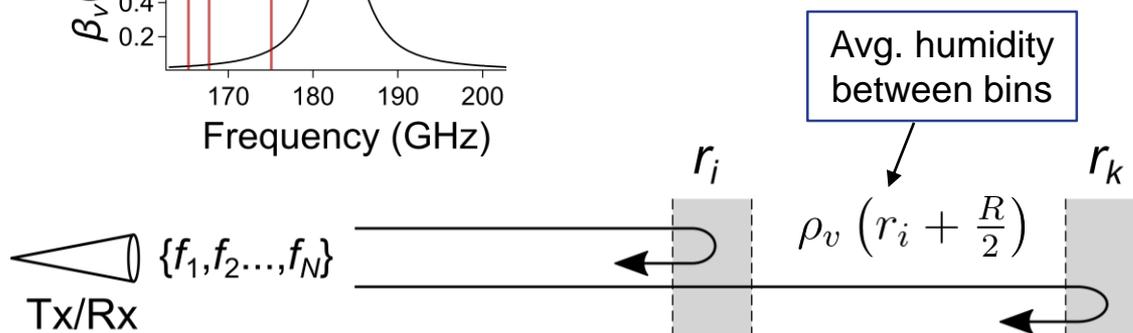


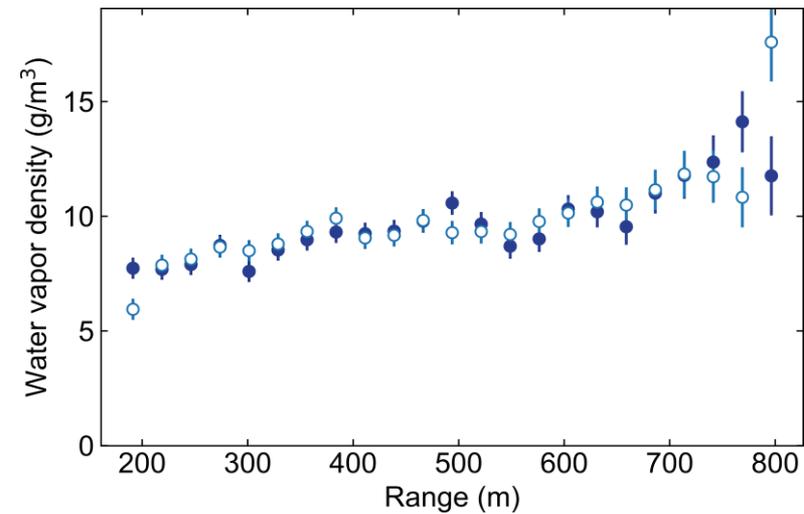
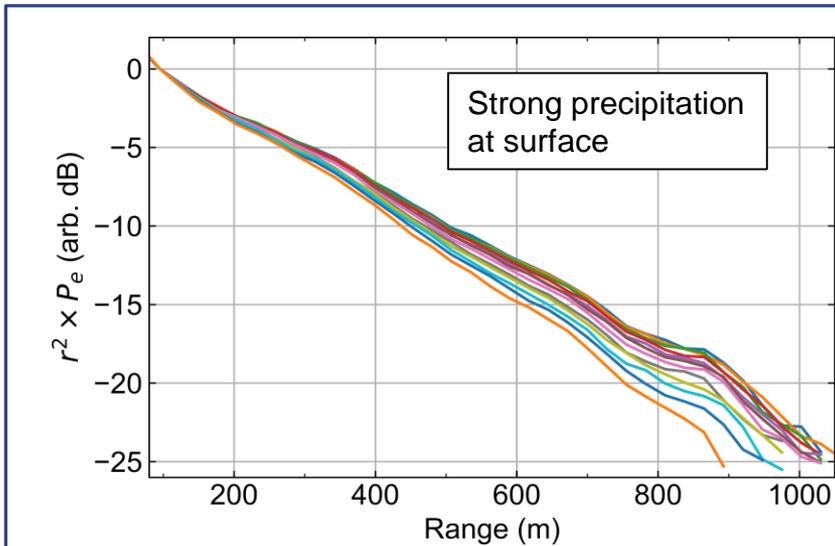
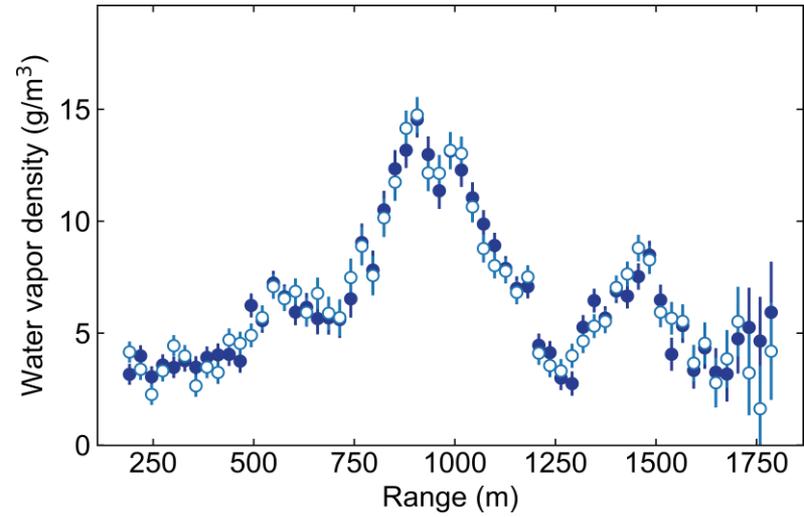
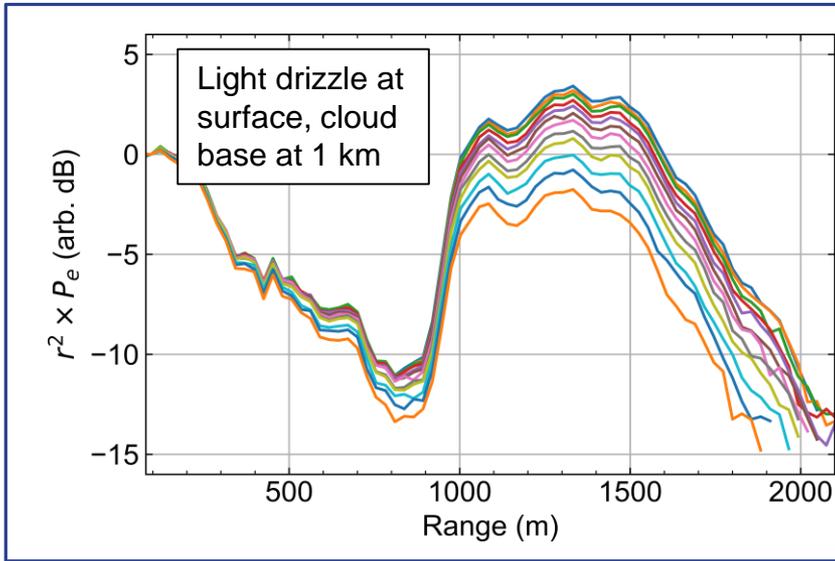
- Fit millimeter-wave propagation model to measured absorption coefficient $\beta_v(f)$ to extract humidity

$$\beta_{\text{meas}} = \frac{-1}{2R} \ln \left(\frac{P_e(r_i + R, f)}{P_e(r_i, f)} \right)$$



Retrieval step size: $r_k - r_i = R$







The present:

- G-Band differential absorption radar proof-of-concept instrument assembled and preliminary field testing successful
- Real-time background noise floor cancellation using bidirectional chirp
- Capable of measuring both precipitating (large hydrometeors/cross section) and non-precipitating (smaller hydrometeors/cross section) clouds
- Humidity profile retrieval algorithm implemented

The future:

- Installation of 61 cm primary aperture and corresponding 20 dB increase in gain
- Field testing with coincident radiosonde measurements for instrument validation
- Testing from an airborne platform – investigate surface returns for total column water retrieval

Thank you to ESTO for funding the project.



**Thank you for your
attention**

Questions?