

Generation of Object-Centric Datasets with Adaptive Sky

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Background image courtesy J. Zehnder, ASU



Outline

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Why Sensor Webs?

- Timeliness respond quickly to short-lived events
- Deficiency overcome limitations of individual sensing agents
- Provide rich multi-modal observations, particularly of objects that evolve in space and time, such as clouds.
- Generate "Object-Centric Datasets"



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Credits: A. Kelley (Morning); A. McCLung (A-Train); J. Zehnder CuPIDO Slide 3



Earth Observing System

- Conceived in late 1980's
- Increase understanding of Earth and its processes through use of new sophisticated spaceborne sensors
- Fundamentally important to use Multiple instruments
 - MODIS (Moderate Resolution Imaging Spectrometer)
 - MISR (Multi-angle Imaging Spectroradiometer)
 - CALIOP (Cloud Aerosol Lidar with Orthogonal Polarizations)
 - CPR (Cloud Profiling Radar)
 - High-resolution Hyperspectral Imagers (ASTER, Hyperion)
 - Many others (and many new instruments in the works)





EOS "Report Card"

- EOS has been very successful in many respects; however, still significant untapped potential.
- Very few studies combine high-resolution information from multiple instruments. Why?
- Data analysis frequently funded through instrument-specific science teams doing stovepipe analysis on "their" instrument data.
- Disparate instrument-specific data organization and packaging schemes, e.g., granules, blocks, images, swaths.
- Difficult even to use data from two instruments on same platform such as MISR and MODIS on Terra due to different way of breaking data into manageable chunks.
- Don't timestamping and georeferencing solve all these issues? (No!)
- Good for ingestion into coarse-scale models (e.g., GCMs with 250km cells) or for processes that are spatially stationary
- Many important natural objects (hurricanes, tornadoes, clouds, etc.) occur at finer scales and are not bound to any particular (lat,lon) location.







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- 524 Reports:131 tornadoes267 severe winds126 large hail
- 23 Reports within +/- 15 minutes of A-Train Overpass

Only ONE report falls within 10km of the effective 1km swath of CPR



Message: A lot of interesting stuff going on; we didn't see much of it!





Adaptive Sky Objectives

- •Enable observations from multiple sensing assets (satellites, in-situ sensors, etc.) to be dynamically combined into "sensor webs".
- Develop an efficient, trusted C-language feature correspondence toolbox that serves sensor web development as LINPACK has served numerical computing.
- •Demonstrate collection and fusion of multi-instrument observations forming novel data products of high scientific value.







Adaptive Sky Sensor Web Scenarios

Combining multi-instrument, multi-platform observations.



Slide 9 Credits: A. Kelley (Morning); A. McCLung (A-Train); J. Zehnder CuPIDO



ASKY currently contains:

- ~20,000 source lines of code (SLOC).
- several full-scale, stand-alone executable programs with source code to demonstrate major features and capabilities.
- additional utilities under libasky_utils support the example programs, but are not part of libasky proper. (e.g. command-line parsing utilities, image input and output (I/O), etc.). •





- Multi-instrument, multi-platform measurements are fundamental to EOS program, but few combined studies.
- Comparisons between EOS-Terra (10:30 LT* equatorial crossing on descending node) and EOS-A-Train (13:30 LT* equatorial crossing on ascending node) provide information about sensor intercalibration; increased science due to the variety of sensors available.

MISR* Stereo-Derived Cloud-top Heights

MODIS* Cloud-top Heights from Pressures



- Comparisons between EOS-Terra and EOS-Aqua have only been done using global data in a mean sense.
- Detailed comparisons raise questions about stationarity of the data, due, in particular, to diurnal and sampling effects.
- Object-centric datasets.





Instrument Coincidences





Going Deeper than Metadata (Data-level Match-ups)

 $\Delta t = 100 \min$ MODIS - Terra MODIS - Aqua





Data-level Match-ups: Many observations take the form of images. •Need fast, robust method for automatic registration.

•Sensor web constraints.

Challenges:

•Different viewpoint; some lighting change. ·Registration.

• Multiple

independent, complex motions.

- ·Non-rigid objects.
- Splits/Merges
- ·Births/Deaths





Feature Detectors and Descriptors



Blobs





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Affine- and Illumination-Resistant Descriptors (e.g., SIFT)









Southern California Fires



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Raw GOES-West sequence during October 2007 Southern California fires.





GOES Stabilized Sequence



Auto-registered sequence during October 2007 Southern California fires.



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Segmentation and Tracking





18:18:02







18:24:02







Image sequence from single CuPIDO ground camera.





Google Earth Visualizations



Google Earth Example from October 28, 2007 showing Terra/A-Train overlap. Time-tagging shows when the individual sensors acquired data relative to one another

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Google Earth Visualizations



Extruded CloudSat ground track, which emphasizes the vertical nature of the CloudSat data relative to the horizontal MODIS and MISR data.

MODIS-derived fire power shown as SketchUp Columns whose height is proportional to the fire power. This indicates the relative intensity of the fire at that location as seen by the instrument from space.



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Adaptive Sky Demonstration Overview



*BTD = Brightness Temperature Difference



Bezymianny Timeline



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Tracking through GOES Sequence



Ash Cloud Tracks (30 hours)







Follow-up Observations of Ash Cloud 3

Terra Overpass 20071016T00:05 UTC



MISR Height Profile



•MISR Stereo Heights indicate a Cloud at ~6 km, with lower clouds at 1-2 km.

•MISR Aerosol Retrievals indicate non-spherical particles in this region, consistent with ash

A-Train Overpass 20071016T01:50 UTC



•CALIOP lidar indicates an extremely thin aerosol layer at an altitude of ~6 km in the region.

•The CloudSat radar does not have any returns in this area, indicating extremely small particles.





Future Work











Conclusions

- Adaptive Sky feature tracking allowed observations made in mid-ocean to be associated unambiguously with an ash cloud from the Bezymianny eruption, even with a time difference of ~30 hrs and a spatial separation of ~400 km.
- First observations of a volcanic ash cloud from the CALIOP lidar on CALIPSO and first *joint observations* with both CALIOP and MISR.
- Without tracking through the GOES BTD sequence, the returns would likely have been attributed to cirrus clouds.
- MISR stereo-derived heights for the ash cloud can be compared directly to the CALIOP lidar heights; MISR aerosol product lends confidence to the assertion this is indeed an ash cloud.

