Pathfinder Advanced Radar Ice Sounder :PARIS

ESTO-2008

R. Keith Raney, C. Leuschen*, and M. Jose

Johns Hopkins University APL 25 June 2008

The Johns Hopkins University APPLIED PHYSICS LABORATORY

*University of Kansas



PARIS: Pathfinder Advanced Radar Ice Sounder

2007 Mission to Greenland

The Way Forward



Objective

Develop techniques to enable and/or to enhance the visibility of internal layering and bottom topography of (*continental*) ice sheets when probed (*sounded*) by a high-altitude radar (*from aircraft or spacecraft*)



Perspective

The Major Challenges: Clutter; Weak SignalsClutter dimensions:Along-track suppressionAcross-track suppression

Weak signal mitigation: Innovative radar design large dynamic range, very low side-lobes, extreme linearity, generous power

NASA-IIP-supported proof-of-concept system: PARIS

150 MHz (vision: Antarctica; planetary prototype) High altitude (first successful demonstration, P-3 aircraft)

ESTO-ESTC, June 2008

Prototype for PARIS: D2P radar altimeter (previous NASA IIP project)





PARIS: Pathfinder Advanced Radar Ice Sounder

Along-track clutter suppression Delay-Doppler processing Radar design: key features

2007 Mission to Greenland

The Way Forward





Along-Track Clutter Suppression: Partially-Coherent Doppler



- Transmit "high" PRF (> Nyquist rate) to unambiguously retain **Doppler spectrum**)
- (A) Reflections from nadir will be at zero-Doppler
- (B) Off-nadir clutter reflections will have |larger| Doppler frequencies
- Filter data in the Doppler domain to favor reflections from layers and depth, and to suppress clutter

Along-Track Clutter Suppression: Doppler



Delay-Doppler Technique Spacecraft altimeter example



In situ sounding: dielectrics of ice differ from air => different velocity of propagation and Doppler scaling in ice. APL

Benefits of partially-coherent Doppler processing



Radar sounder architecture (minimize RF operations)



Design: isolate aliased (under-sampled) signals







PARIS: Pathfinder Advanced Radar Ice Sounder

Along-track clutter suppression Delay-Doppler processing Radar design: key features

2007 Mission to Greenland Quick-time and initial results

The Way Forward



PARIS on the NASA P-3



 Univ. of Kansas' CRESIS antennas (shared with PARIS)



ESTO-ESTC, June 2008 APL

PARIS: Inside the P-3



PARIS-I Radar in Operation

| 📕 Applet Viewer: ParisV2.class 🧐 | | | | | | | . 🗆 🗴 |
|---|--|-----------|--|--------------|-------------|-------|---------|
| Applet | | | | | | | |
| Chirp VGAs Combined VGAs Histogram | Config Main Confi | g VGA Cor | nfig T/R Ra | inging Statu | s Statu | 5 | |
| With Combined 15 000 | Parameter | Hex | Decimal | Enginee | rina | Entry | Send |
| VGAS Committee 15000 | chirp_period | 0×2089 | 8329 | 124,935 | U 5 | | Send |
| / | chirp_rate | 0×2069 | 8329 | 8004 | Hz | | Send |
| | osk_start | 0x0210 | 528 | 7,920 | 115 | | 10 |
| | pulse_width | | | 29,995 | us - | | Send. |
| Geita(dB) | sample_start_time | 0x0AF0 | 2800 | 42,000 | \$15 | | Send |
| | sample_count | 0x0348 | 840 | 63,000 | 115 | | Send |
| | DAC1_data | 0x0870 | 135*16 | +10.00 | dB | | Send |
| | DAC1_Hait_Bax | 0x01 | 1 | 1,275 | JUS . | | Send |
| 15.000 | DAC1_Wait_inc | 0×7F | 127 | | | | Send |
| 5 103 km Banav 14 537 km | DAC1_min_time | 0×10A8 | 4267 | 64.005 | us | | Send |
| | DAC1_Rax_time | 0×1CA5 | 7333 | 109,995 | µ5 | | . Send. |
| Acquired Data 4136 | DAC1_ranp_rate | | - | 1,556 | dB/µs | | |
| | DACZ_data_I | 030980 | 155*16 | +5.00 | dB | | Send |
| and the filler | DAC2_time | 0x1CA5 | 7333 | 109.995 | μs | | Send |
| | DAC2_GBTR_2 | 0x0980 | 155*16 | -5,00 | 48 | | Send |
| Log | Data Recording | | Enable | Disable | 1 | | |
| | Auto Ranging (VGAN T | R.ND | Enable | Disable | | | |
| 5.103 km Max @ Range 5.676 km 16.604 km 5.1 km | Extra Register Configuration Setup Sample Window Width Signal Averaging (32) Committing Mode | 00000 | ptions > ptions > ptions > ptions > | Config OK | | | |
| | T/R Switch Set | - | TX On | TX Off | Def | ealte | |
| CARDING STREET, SALES AND DESCRIPTION OF THE OWNER. | Power Display | | Log | Linear | Lei | | |
| 2 | Waterfall Display Rate | 0 | ptions 🕨 | | | | |
| 14.5 km | Waterfall Look Up Table | 0 | ptions 🕨 | | | | |
| monthal stratted | | | | | | | _ |
| ppier starteu. | | | | | | | |
| | | TO | 1 | - 20 | 00 | A | ۲ |

ESTO-ESTC, June 2008

Arctic '07 Mission Tracks

- PARIS shared the NASA P-3 w/ Airborne Topographic Mapper (ATM)
- PARIS operated during ATM (low-altitude) flights
- 925 GB of PARIS data collected over 10 days
- High altitude data acquired 04 and 07 May



Raw Data 07 May 2007 14:10:45-14:16:00

(sub-sample – first four seconds)



Delay-Doppler (partially-coherent) Sounding



ESTO-ESTC, June 2008



PARIS: Pathfinder Advanced Radar Ice Sounder

Background Along-track clutter suppression Radar design: key features

2007 Mission to Greenland Quick-time and initial results

The Way Forward

Refine along-track processing algorithm Cross-track clutter suppression Conclusions



Cross-Track Clutter Suppression: Polarization (*new concept*)



Why Transmit Circular Polarization?

- Single-bounce (specular) reflection always reverses the sense of the illuminating (circular) polarity
- (Linear polarization sense-reversal is not observable)
- > Most reflections from nadir (and from depth) will be specular => opposite sense circularly polarized
- > Specular reflections => high coherence (~ degree of polarization)
- > Reflections from clutter almost always will have different polarization properties

Dual Hybrid-Polarity Radar Sounder



On Polarimetric Parameters • Stokes parameters fully characterize the received EM **field** => *innovation for radar sounder data* Stokes parameters support parametric discrimination *e.g.:* > Measurement of relative $(E_X :: E_Y)$ phase δ > Degree of polarization *m* **Hybrid Polarity** $S_1 = \langle |E_X|^2 + |E_Y|^2 \rangle + 2N_0$ $m = (S_2^2 + S_3^2 + S_4^2)^{\frac{1}{2}} / S_1$ $S_2 = \langle |E_x|^2 - |E_y|^2 \rangle$ $S_3 = 2 \text{ Re} < E_X E_Y >$ $\delta = \arctan(S_4 / S_3)$ $S_4 = -2 \text{ Im} < E_x E_v >$

ESTO-ESTC, June 2008

Clutter vs Signal in m-delta Feature Space

Transmit left-circular polarization (Example: Real non-ice data)



Hypothesis: Desired depth signals will differ from clutter in a decomposition feature space. Selective filtering in a polarimetric feature space can enhance depth returns, and suppress clutter

ESTO-ESTC. June 2008

Clutter Suppression Issues (Recap)

A good sounder => a "clean" radar: dynamic range, linearity, extreme side-lobe control, etc

Doppler (along-track): Well established

Proven technique (PARIS, Marsis, etc.) Ground processing Optimal performance => must match ice index of refraction

Polarization (across-track): New strategy Developmental technique: requires proof-of-concept Ground processing Optimal performance may imply adaptive selectivity in response to clutter and depth polarization signatures



Conceptual Flow of Clutter Suppression



Comments on hybrid-polarity

- Hybrid-polarity is a proven methodology for (*compact*) polarimetric SAR (*classification by matrix decomposition*)
- The cross-track polarimetric method is fully compatible with along-track enhancement techniques (*Doppler and/or polarimetric*) for a radar sounder
- Sidelobes from the surface return can be suppressed if their polarimetric signature differs from depth signals
- The same technique could help to suppress the triplebounce reflection of the aircraft (*ideal for a UAV or airborne radar sounder application*)

Conclusions

- > Delay-Doppler is successful for suppressing alongtrack clutter, enhancing radar sounding signals
- > High-altitude radar sounding proven to be feasible
- > PARIS design successfully demonstrates robust (*and generalizable*) radar sounder principles
- Cross-track clutter suppression by polarimetric selectivity is a promising (*but as yet untested*) technique
- ➢ In practical situations for which clutter vs signal polarimetric phase distributions are significantly different, then large SCR gain is likely
- > Recommend continued development of these themes